

Three-Station Interferometry and Tomography Using Coda and Direct Waves

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Summary

Traditional two-station ambient noise interferometry estimates the Green's function between a pair of synchronously deployed seismic stations. Three-station interferometry considers records observed three stations at a time, where two of the stations are considered receiver-stations and the third is a source-station. Cross-correlations between records at the source-station with each of the receiver-stations are correlated or convolved again to estimate the Green's function between the receiver-stations, which may be deployed asynchronously. We use data from the EarthScope USArray in the western US to compare Rayleigh wave dispersion obtained from two-station and three-station interferometry. Three three-station interferometric methods are distinguished by the data segment utilized (coda-wave or direct-wave) and whether the source-stations are constrained to lie in stationary phase zones approximately inline with the receiver-stations. The primary finding is that the three-station direct wave methods perform considerably better than the three-station coda-wave method and two-station ambient noise interferometry, in terms of signal-to-noise ratio, bandwidth, and the number of measurements obtained, but possess small biases relative to two-station interferometry. We present a ray-theoretic correction method that largely removes the bias below 50 s period and reduces it at longer periods. Three-station direct-wave interferometry provides substantial value for imaging the crust and uppermost mantle, and its ability to bridge asynchronously deployed stations may impact the design of seismic networks in the future.

Key words: Seismic noise; Seismic interferometry; Seismic tomography; Surface waves and free oscillations; Coda waves.

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1 Introduction

Inter-station seismic interferometry is designed to extract an estimate of the Green’s function between pairs of seismic stations or receivers. Generally speaking, there are two established methods to perform this task, which we will call “*two-station interferometry*” and “*three-station interferometry*”. In this paper, we attempt to clarify and illuminate three-station interferometry, discuss and characterize important variants of the method, and compare the characteristics amongst the variants and to two-station interferometry using data from the EarthScope Transportable Array (TA) in the US.

Two-station interferometry is the traditional method of “*ambient noise interferometry*” or “*ambient noise correlation*”. It is the more commonly applied method and is based on a single cross-correlation between ambient noise recorded at two stations. The cross-correlation can be converted to an estimate of the Green’s function of the medium if the time series is long enough (e.g., [Shapiro & Campillo, 2004](#)). In this case, one of the stations acts as a virtual source of the seismic energy and the other as the receiver. When many pairs of stations are considered, it is the basis for *ambient noise tomography* of surface waves, and many applications of this method have emerged since [Shapiro et al. \(2005\)](#); [Sabra et al. \(2005\)](#); [Yao et al. \(2006\)](#).

Three-station interferometry, in contrast, considers recordings from three seismic stations at a time. This method takes the cross-correlation between recordings of ambient noise at one station, which acts as a virtual source and which we call the “*source-station*”, with recordings from two other stations, which are called the “*receiver-stations*”. These two cross-correlations, or particular segments of them, are then cross-correlated again (or, as discussed further below, convolved). Stacking the resulting waveforms from many source-stations for the same pair of receiver-stations provides an estimate of the Green’s function between the two receiver-stations. This method, therefore, is based on cross-correlations performed three at a time, where the last one has been referred to as the “*correlation of correlations*” ([Stehly et al., 2008](#)) but in certain circumstances will be a convolution of correlations. We refer to this method generally speaking as “*three-station interferometry*”, to distinguish it from traditional two-station ambient noise methods. When the final cross-correlation is between the coda-wave parts of the first two correlations the method is commonly referred to as the “*correlation of the coda of correlations*” or C^3 ([Stehly et al., 2008](#)).

60 **Fig. 1** illustrates some of the notation introduced in this paper. For two-station
 61 interferometry, we denote the cross-correlation between a pair of seismograms observed
 62 at stations r_i and r_j as $C_2(r_i, r_j)$. With an appropriate phase-shift, $C_2(r_i, r_j)$ can be con-
 63 verted to an estimate of the Green’s function between the two stations, $\hat{G}_2(r_i, r_j)$, where
 64 we suppress the time-dependence of the correlations and the estimated Green’s function.
 65 For three-station interferometry, cross-correlations between observations at a source-station,
 66 s_k ($1 \leq k \leq N$), with the two receiver-stations, $C_2(s_k, r_i)$ and $C_2(s_k, r_j)$, are corre-
 67 lated again (or in some circumstances convolved). This produces the three-station “*source-*
 68 *specific interferogram*”, $C_3(r_i, r_j; s_k)$, for source-station s_k , which provides information
 69 about the medium between the two receiver-stations. (The subscript “3” distinguishes
 70 the final cross-correlation or convolution from the first two correlations.) The “*compos-*
 71 *ite Green’s function*” for three-station interferometry is produced by taking a weighted
 72 sum over the contributing source-specific interferograms from the N source-stations:

$$\hat{G}_3(r_i, r_j) = \sum_{k=1}^N w_k C_3(r_i, r_j; s_k) \quad (1)$$

73 where w_k is a weight. For this equation to hold, C_3 must have an appropriate phase-shift
 74 applied prior to the summation.

75 The advantages of two-station interferometry include its simplicity and general ap-
 76 plicability. The principal advantage of the three-station method over the two-station method
 77 is that the two receiver-stations do not have to operate at the same time, although they
 78 do have to operate synchronously with each source-station for some length of time. Thus,
 79 three-station interferometry can be applied to asynchronously deployed stations (Ma &
 80 Beroza, 2012), which provides the opportunity for what Entwistle et al. (2015) call “ret-
 81 ropective seismology”. In terms of applications, the method will be most impactful in
 82 settings where there is a long-term backbone seismic network to provide the source-stations
 83 and shorter term deployments from which the receiver-stations are taken.

84 In practice, the data processing involves three noteworthy subtleties. (1) The cross-
 85 correlations of seismic noise data that form the basis for both the two-station and three-
 86 station methods involve refined data processing methods that aim to speed convergence
 87 and reduce sensitivity to earthquakes and localized persistent noise sources (e.g., Ritz-
 88 woller & Feng, 2019). We discuss the methods of data processing that we use in **sections**
 89 **2 and 3** below, but we do not attempt to optimize data processing procedures for three-
 90 station interferometry.

91 (2) We must specify which parts of the cross-correlations of seismic noise, $C_2(s_k, r_i)$
 92 and $C_2(s_k, r_j)$, that are correlated or convolved to produce the source-specific interfer-
 93 ogram for source s_k , $C_3(r_i, r_j; s_k)$. **Fig. 2** identifies the two parts of the cross-correlations
 94 relevant to this study: the coda-wave (CW) and the direct-wave (DW) parts. If coda waves
 95 are correlated, we refer to the method to produce an estimated Green’s function as “*coda-*
 96 *wave interferometry*” and if direct waves are correlated or convolved we call it “*direct-*
 97 *wave interferometry*”.

98 (3) Finally, it is important to specify how to determine the weights, w_k , that con-
 99 vert individual source-specific interferograms to the estimated Green’s function. One as-
 100 pect of the choice of weights is the geometrical relationship between the receiver-stations
 101 and each source-station. For coda-wave interferometry there is no geometrical constraint
 102 so that all source-stations are used for a given receiver-station pair irrespective of their
 103 relative position; that is, the geometrical-weights are all unity (**Fig. 3a**). However, for
 104 direct-wave interferometry we impose the constraint that the source-stations lie within
 105 appropriately defined “stationary phase zones” so that sources outside those zones are
 106 given zero geometrical-weight and sources inside the zones are given unit geometrical-
 107 weight. The stationary phase zone is a Fresnel ellipse for source-stations between the receiver-
 108 stations (**Fig. 3c**) or hyperbolae for source-stations not between the receiver-stations
 109 (**Fig. 3b**), where the receiver-stations are the foci of both the ellipse and the hyperbo-
 110 lae. Another aspect of these weights is based on a measure of the quality of each source-
 111 specific interferogram, $C_3(r_i, r_j, s_k)$. Both aspects of assigning weights are discussed in
 112 greater detail in **section 3.2**.

113 It is useful to define nomenclature to distinguish the interferometric methods con-
 114 sidered here. Traditional two-station ambient noise (AN) interferometry is denoted:

$$\mathcal{I}_2^{AN},$$

115 where the “2” represents the number of stations used. Three-station methods require the
 116 specification of two additional fields, “*type*” and “*geometry*”, so that three-station inter-
 117 ferometric methods are denoted generally as:

$$geometry \mathcal{I}_3^{type}.$$

118 Here, “type” indicates either coda-wave (CW) or direct-wave (DW) interferometry, “ge-
 119 ometry” represents the shape of the stationary phase zone, and the “3” indicates the num-
 120 ber of stations used in the method prior to stacking over source-stations. Of course, in

121 the stacking of eq. (1) multiple source-stations will typically be used, but data analy-
 122 sis is performed three stations at a time. There is no geometrical constraint for coda-
 123 wave interferometry; thus this field is left blank in this case. For direct-wave interfer-
 124 ometry the geometrical constraint is either an ellipse (ell) or a hyperbola (hyp).

125 Therefore, we identify three general methods of three-station interferometry to esti-
 126 mate Green's functions. First, three station coda-wave interferometry is denoted as

$$\mathcal{I}_3^{CW}.$$

127 Therefore, there is the following relationship between our notation and earlier notation:
 128 $\mathcal{I}_3^{CW} \equiv C^3$. Second, three-station direct-wave interferometry with sources in the ellip-
 129 tical stationary phase zone between the receiver-stations is represented as

$$ell\mathcal{I}_3^{DW}.$$

130 Finally, we indicate three-station direct-wave interferometry with sources in the hyper-
 131 bolic stationary phase zones radially outside the receiver-stations as

$$hyp\mathcal{I}_3^{DW}.$$

132 When we refer to direct-wave interferometry generally without distinguishing between
 133 the geometry of the stationary phase zones, we will use the symbol \mathcal{I}_3^{DW} , leaving the ge-
 134 ometry field blank.

135 Three-station coda-wave interferometry (\mathcal{I}_3^{CW}) was initiated by [Stehly et al. \(2008\)](#)
 136 and has been fairly well studied (e.g., [Garnier & Papanicolaou, 2009](#); [Froment et al., 2011](#);
 137 [Ma & Beroza, 2012](#); [Zhang & Yang, 2013](#); [Entwistle et al., 2015](#); [Haendel et al., 2016](#);
 138 [Sheng et al., 2017, 2018](#); [Spica et al., 2017](#)). Applications of \mathcal{I}_3^{CW} to surface wave tomog-
 139 raphy or 3-D model construction remain rare, however, in particular at regional or con-
 140 tinental scales. To the best of our knowledge, the principal exceptions are two studies
 141 that combine group velocity measurements from \mathcal{I}_3^{CW} with traditional ambient noise in-
 142 terferometry (\mathcal{I}_2^{AN}) to improve 3-D models of Mexico and the southern US ([Spica et al.,](#)
 143 [2016](#)), and of the Iranian Plateau ([Ansaripour et al., 2019](#)).

144 In comparison, three-station direct-wave interferometry (\mathcal{I}_3^{DW}) has received much
 145 less attention. [Froment et al. \(2011\)](#) discussed the possibility for using direct versus coda
 146 waves, and differentiated between two types of correlations of correlations: C_{coda}^3 and
 147 C_{all}^3 , where C_{coda}^3 denotes the correlation of the coda of correlations and C_{all}^3 refers to

148 correlating the entirety of the correlations. Thus, as noted above, their C_{coda}^3 is similar
 149 to our \mathcal{I}_3^{CW} and because the direct-waves dominate the coda-waves in the correlations,
 150 their C_{all}^3 is in some ways similar to our \mathcal{I}_3^{DW} . They, however, do not discuss constrain-
 151 ing the source-stations in direct-wave interferometry to lie in stationary phase zones, al-
 152 though other studies do (e.g., [Curtis & Halliday, 2010](#); [Entwistle et al., 2015](#)). Moreover,
 153 the latter studies also recognize that for the elliptical stationary phase zone, when source-
 154 stations lie generally between the receiver-stations, the original cross-correlations should
 155 be convolved with one another rather than cross-correlated. Therefore, for $^{hyp}\mathcal{I}_3^{DW}$ the
 156 three data operations are all cross-correlations, but for $^{ell}\mathcal{I}_3^{DW}$ the third data operation
 157 is a convolution. Discussion of the role of convolution in interferometry goes back at least
 158 to [Slob and Wapenaar \(2007\)](#). [Entwistle et al. \(2015\)](#) applied aspects of direct-wave in-
 159 terferometry to data from the EarthScope Transportable Array, but to the best of our
 160 knowledge \mathcal{I}_3^{DW} has not yet been applied tomographically or in the context of inversions
 161 for 3-D models and its properties remain poorly understood.

162 The purpose of this paper is to determine and compare empirically the character-
 163 istics of the three-station methods to each other and to two-station interferometry. From
 164 the outset, it is evident that coda-wave interferometry has the advantage that any ge-
 165 ometrical relationship can exist between the source-stations and the receiver-stations,
 166 whereas for direct-wave interferometry only a small subset of stations can be used as source-
 167 stations for each pair of receiver-stations. In coda-wave interferometry, however, signals
 168 emerge very slowly with the addition of source-stations, which means that many more
 169 source-stations are needed to recover reliable estimated Green’s functions. Therefore, the
 170 relative merits of direct-wave interferometry and coda-wave interferometry (which of the
 171 methods will be preferable, in what ways, and in which settings) need to be determined
 172 empirically.

173 We address these questions by applying \mathcal{I}_2^{AN} , \mathcal{I}_3^{CW} , $^{ell}\mathcal{I}_3^{DW}$, and $^{hyp}\mathcal{I}_3^{DW}$ across the
 174 central and western US to all stations west of 95°W longitude from the EarthScope Trans-
 175 portable Array to measure Rayleigh wave dispersion from 8 s to 80 s period and present
 176 associated phase speed maps from 10 s to 60 s period. We pay particular attention to
 177 the agreement between the three-station results and the two-station results, including
 178 systematic differences (bias) and fluctuation, and to the distributions of measurements
 179 as functions of signal-to-noise ratio (SNR), band-width, and the number of measurements
 180 produced for asynchronously deployed receiver-stations.

181 2 Data

182 Three-station interferometry (\mathcal{I}_3) is based on data output from two-station inter-
 183 ferometry (\mathcal{I}_2). As the basis for the three-station interferometry in this study, we use
 184 the two-station database of ambient noise cross-correlations (C_2) constructed by [Shen](#)
 185 [and Ritzwoller \(2016\)](#). Stations in the database of [Shen and Ritzwoller \(2016\)](#) extend
 186 across the contiguous US, but we use only a subset of them in the central and western
 187 US (west of 95° W longitude), which defines our region of study (**Fig. 4**). We use all 1047
 188 EarthScope USArray stations in this region deployed from 2005 to 2010, including 979
 189 Transportable Array (_US-TA) stations and 68 Reference Network (_US-REF) stations.
 190 We retain a two-station cross-correlation only if its signal-to-noise ratio (SNR) is greater
 191 than 10, where SNR is defined as the ratio of the maximum amplitude of the waveform
 192 in the direct-wave time window to the root-mean square of the waveform in the coda-
 193 wave window (**Fig. 2**). SNR defined in this way is independent of frequency. Among
 194 the 547,581 possible combinations of pairs from the 1047 stations, 66% (364,103) oper-
 195 ated synchronously so that two-station ambient noise interferometry could be employed.
 196 Of these, we retained 325,446 (89%) cross-correlations that met the SNR criterion. In
 197 contrast, 34% (183,478) of the station-pairs were deployed asynchronously.

198 The deployment of the Transportable Array started from the West Coast and rolled
 199 eastward, with stations deployed temporarily for ~ 2 years (**Fig. 4**). This rolling pat-
 200 tern provides an ideal geometry for direct-wave interferometry with an elliptical station-
 201 ary phase zone, $^{ell}\mathcal{I}_3^{DW}$, in which source-stations lie approximately between receiver-stations.
 202 In contrast, the Reference Network was deployed permanently and was scattered across
 203 the US with a station spacing of ~ 300 km. This is a good geometry for coda-wave in-
 204 terferometry, \mathcal{I}_3^{CW} , and direct-wave interferometry with a hyperbolic stationary phase
 205 zones, $^{hyp}\mathcal{I}_3^{DW}$, in which source-stations lie approximately radially outward from receiver-
 206 stations.

207 [Shen and Ritzwoller \(2016\)](#) used a common method of ambient noise data process-
 208 ing ([Bensen et al., 2007](#)). Briefly, continuous records of vertical component seismograms
 209 are cut to day-long segments and downsampled from 40 Hz to 1 Hz. Then the instru-
 210 ment response, mean and trend are removed. To minimize the effects of strong directional
 211 sources (in particular earthquakes) and to broaden the usable bandwidth, temporal nor-
 212 malization and spectral whitening are applied. The temporal normalization uses a 80 s

213 running time window, which strongly attenuates signals with periods above 80 s. For this
 214 reason we will focus our interpretation on measurements only up to 80 s period and show
 215 tomographic results only up to 60 s period.

216 After pre-processing, daily seismograms from all available combinations of station-
 217 pairs (r_i, r_j) are cross-correlated to produce $C_2(r_i, r_j)$, between correlation lag times of
 218 ± 3000 s. Daily correlations are then stacked to generate two-station estimated Green’s
 219 functions between each pair of stations ($\hat{G}_2(r_i, r_j)$). Finally, we compute the so-called
 220 “symmetric component” of the estimated Green’s function by averaging the estimated
 221 Green’s function at positive and negative correlation lags for simplicity. We will also re-
 222 fer to this symmetric component estimated Green’s function as $\hat{G}_2(r_i, r_j)$, even though
 223 it is defined only for positive lag. This database of symmetric component estimated Green’s
 224 functions is the basis for the three-station analysis (**section 3**).

225 **3 Data Processing for Three-Station Interferometry**

226 The input for three-station interferometry are the two-station symmetric compo-
 227 nent cross-correlations (or estimated Green’s functions) taken from the database of [Shen](#)
 228 [and Ritzwoller \(2016\)](#) with $\text{SNR} > 10$. As inter-station cross-correlations, these func-
 229 tions are denoted by C_2 and as estimated Green’s functions by \hat{G}_2 . Three-station source-
 230 specific interferograms (C_3) are cross-correlations of the coda-wave parts of the inter-
 231 station cross-correlations, or cross-correlations or convolutions of the direct-wave parts
 232 of the inter-station cross-correlations. Three-station data processing aims to compute
 233 the composite Green’s function between pairs of receiver-stations by stacking the three-
 234 station interferograms over contributions from various source-stations.

235 For concreteness, consider a receiver-station pair (r_i, r_j) and a set of source-stations,
 236 $\{s_k\}_{k=1}^N$, that operate synchronously with both r_i and r_j at least for some time. **Fig.**
 237 **1b** depicts this situation, where one source-station is shown. Let the coda-wave parts
 238 of the two-station cross-correlations be denoted $C_2^{CW}(s_k, r_i)$ and $C_2^{CW}(s_k, r_j)$, and the
 239 direct-wave parts be written $C_2^{DW}(s_k, r_i)$ and $C_2^{DW}(s_k, r_j)$, where the coda-wave and
 240 direct-wave segments are defined in **Fig. 2**. The three-station data processing procedure
 241 breaks into three principal steps (**sections 3.1 - 3.3**).

3.1 Construcing Source-Specific Interferograms

The first step in three-station data processing is devoted to cross-correlating or convolving segments of the two-station cross-correlations. It is broken into three categories depending on whether one considers the direct- or coda-wave segments of the two-station cross-correlations and the geometrical relationship between the receiver-station pair and each source-station. For direct-waves, the geometrical relationship is summarized in terms of hyperbolic or elliptical stationary phase zones (**Fig. 3b,c**).

(1) The first category is, for each source-station, to compute the three-station source-specific interferograms based on the coda-waves in the two-station cross-correlations. That is, correlate $C_2^{CW}(s_k, r_i)$ and $C_2^{CW}(s_k, r_j)$ for all s_k to produce $C_3^{CW}(r_i, r_j; s_k)$ for $1 \leq k \leq N$. An example record-section containing three-station coda-wave source-specific interferograms is presented in **Fig. 5a**, where each trace is for a separate source-station.

(2) The second category is to compute the three-station source-specific interferograms based on the direct-waves in the two-station cross-correlations for the source-stations in the hyperbolic stationary phase zones. For each source-station s_k in the stationary-phase hyperbolae for the receiver-station-pair, cross-correlate $C_2^{DW}(s_k, r_i)$ and $C_2^{DW}(s_k, r_j)$ to produce $^{hyp}C_3^{CW}(r_i, r_j; s_k)$. An example record-section for three-station direct-wave source-specific interferograms computed by cross-correlation is shown in **Fig. 5b**, where each trace is for a separate source-station. For this record-section, cross-correlations are computed based on source-stations irrespective of whether they lie in the stationary-phase hyperbolae. However, the green-shaded regions identify the stationary phase zones.

(3) The third category is similar to the second, but we compute the three-station source-specific interferograms based on the direct-waves in the two-station cross-correlations for the source-stations in the elliptical stationary phase zone. For each source-station s_k in the stationary-phase ellipse for this receiver-station-pair, convolve the direct-wave parts of $C_2(s_k, r_i)$ and $C_2(s_k, r_j)$ to produce $^{ell}C_3^{CW}(r_i, r_j; s_k)$. An example record-section for three-station source-specific direct-wave interferograms computed by convolution is shown in **Fig. 5c**, where each trace is for a separate source-station. As in **Fig. 5b**, convolutions are presented irrespective of whether the source-station lies in the stationary-phase ellipse, but the green-shaded region identifies the stationary phase zone.

272 Convolution of the direct-wave parts of the two-station records when source-stations
 273 lie in the elliptical stationary phase zone has been formally justified by other studies (e.g.,
 274 [Halliday & Curtis, 2009](#); [Curtis & Halliday, 2010](#)). We provide a heuristic argument for
 275 illumination. When a source-station lies radially outward from a pair of receiver-stations,
 276 it is the time-difference between the travel times from the source-station to the two receiver-
 277 stations that approximates the travel time between the two receiver-stations. Cross-correlation
 278 of two records finds the time-difference between them, therefore when source-stations lie
 279 outside the receiver-stations it is the appropriate method to apply. In contrast, convo-
 280 lutions find the sum of the times. When a source-station lies between two receiver-stations,
 281 we wish to find the sum of the times from the source-station to each receiver-station, so
 282 that convolution is the appropriate method to apply in this case.

283 Both the hyperbolic and elliptical stationary phase zones are straightforward to de-
 284 fine. An ellipse is defined as the locus of points where the sum of the distances to the
 285 foci is constant. Let d_{ij} be the great-circle distance between the two receiver-stations,
 286 d_{ki} be the distance between a point s_k on the ellipse and receiver-station r_i , and d_{kj} be
 287 the distance between s_k and receiver-station r_j . Then we define the elliptical station-
 288 ary phase zone for method $^{ell}\mathcal{I}_3^{DW}$ as

$$d_{ki} + d_{kj} \leq (1 + \alpha)d_{ij}, \quad (2)$$

289 where $\alpha \geq 0$ and we choose $\alpha = 10^{-2}$. Thus, if source-station s_k lies within the ellip-
 290 tical stationary phase zone, the sum of distances from s_k to r_i and to r_j is less than 1%
 291 longer than the distance between the receiver-stations.

292 Similarly, a hyperbola is defined as the locus of points where the difference of the
 293 distances to the foci is constant. We therefore define the hyperbolic stationary phase zones
 294 for method $^{hyp}\mathcal{I}_3^{DW}$ as

$$|d_{ki} - d_{kj}| \geq (1 - \alpha)d_{ij}, \quad (3)$$

295 where $\alpha \in [0, 1]$ and again we choose $\alpha = 10^{-2}$. This means that if source-station s_k
 296 lies within the hyperbolic stationary phase zone, the difference of distances from s_k to
 297 r_i and to r_j is greater than 99% of the distance between the receiver-stations. On a sphere,
 298 the locus of points where the difference of the distances to the foci is constant, however,
 299 approximates a hyperbola only near the foci.

300 The stationary phase zones can be defined alternatively using azimuthal angle θ
 301 (**Fig. 3**) instead of α . For the methods \mathcal{I}_3^{CW} and $^{hyp}\mathcal{I}_3^{DW}$, θ is the angle from the source-

302 station to the mid-point between the receiver-stations (**Fig. 3a,b**), which defines the slopes
 303 of the asymptotes of a hyperbola. It is related to α by $\cos \theta = 1 - \alpha$, where $\theta \in [0, 2\pi]$.
 304 The definition of angle θ for a given source-station for method $^{ell}\mathcal{I}_3^{DW}$ is motivated by
 305 the symmetry in eqs. (4) and (5) below. To do so, first identify the ellipse on which the
 306 source-station lies with the two receiver-stations as foci. Then find the intersection point
 307 between the ellipse and the perpendicular bisector of the line segment linking the two
 308 receiver-stations. Angle θ is the angle between a receiver-station and this intersection
 309 point. **Fig. 3c** shows an example of this intersection point, but does not identify the lo-
 310 cation of the source-station or the ellipse on which it lies. In this case, θ is related to α
 311 by $\cos \theta = 1/(1+\alpha)$, where $\theta \in [0, \frac{\pi}{2}]$. For the same α , θ is generally larger for $^{hyp}\mathcal{I}_3^{DW}$
 312 than for $^{ell}\mathcal{I}_3^{DW}$. Our choice of $\alpha = 10^{-2}$ corresponds to a maximum $\theta \approx 8^\circ$ for both
 313 $^{hyp}\mathcal{I}_3^{DW}$ and $^{ell}\mathcal{I}_3^{DW}$.

314 We use eqs. (2) and (3) with $\alpha = 10^{-2}$ to define the stationary phase zones in this
 315 paper for methods $^{ell}\mathcal{I}_3^{DW}$ and $^{hyp}\mathcal{I}_3^{DW}$, respectively. These definitions are chosen for
 316 simplicity and because they appear to provide reliable results in the applications we con-
 317 sider. However, the choice of the value of α is ad-hoc as is its frequency-independence.
 318 More elaborate, perhaps frequency-dependent, definitions may prove to be preferable.

319 The approximate arrival time, δt , for method $^{hyp}\mathcal{I}_3^{DW}$ is known (e.g., Yao & van
 320 der Hilst, 2009):

$$\delta t = \frac{d_{ij}}{v} \cos \theta, \quad (4)$$

321 for a plane-wave in a medium with constant wave speed v , where d_{ij} is the inter-receiver-
 322 station distance and θ is shown in **Fig. 3b**. The grey line plotted in **Fig. 5b** is for this
 323 formula. Analogously, the approximate arrival time t_{sum} for method $^{ell}\mathcal{I}_3^{DW}$ is:

$$t_{sum} = \frac{d_{ij}}{v} \sec \theta, \quad (5)$$

324 for θ shown in **Fig. 3c**. The grey line plotted in **Fig. 5c** is for this formula.

325 3.2 Stacking Weights

326 Appropriate stacking weights w_k must be computed for each source-station s_k for
 327 each of the three-station methods (\mathcal{I}_3^{CW} , $^{hyp}\mathcal{I}_3^{DW}$ and $^{ell}\mathcal{I}_3^{DW}$) to compute the compos-
 328 ite Green's functions. The principal weight that we use is to set w_k equal to the recip-
 329 eral of the root-mean-square (rms) of the noise in the coda-wave part of each source-
 330 specific interferogram, $C_3(r_i, r_j; s_k)$ for receiver-stations r_i and r_j . Defined in this way,

331 we down-weight each contributing cross-correlogram by the rms of trailing noise. We do
 332 not, however, normalize the amplitude of the cross-correlograms. Therefore, down-weighting
 333 by the rms of trailing noise is approximately equivalent to normalizing the amplitudes
 334 of the cross-correlograms then weighting by peak signal-to-rms trailing noise ratio (SNR).
 335 Because the peak signal grows approximately linearly with the time series length of the
 336 records used to compute the cross-correlations, and rms trailing noise grows approximately
 337 as the square root of the time series length, SNR grows approximately as the square root
 338 of time series length (e.g., Snieder, 2004; Bensen et al., 2007). Thus, the use of this weight-
 339 ing scheme tends to accentuate the contribution from longer cross-correlations, but less
 340 strongly than if we had not normalized by peak amplitude and inversely by the rms of
 341 the trailing noise.

342 There are three other aspects of the data processing that can be considered to be
 343 stacking weights. First, for the direct-wave three station methods, we only include a source-
 344 station in the stack if it lies within an appropriately defined stationary phase zone, which
 345 is referred to as geometrical-weighting in the Introduction. This choice can be thought
 346 of as applying binary weights to source-stations depending on their position relative to
 347 the receiver-stations. Second, also as mentioned above, unless the two constituent two-
 348 station interferograms, $C_2(s_k, r_i)$ and $C_2(s_k, r_j)$, both have $\text{SNR} \geq 10$, the weight of the
 349 corresponding three-station interferogram, $C_3(r_i, r_j; s_k)$, is set to zero; otherwise it is unity.
 350 Third, for the coda-wave three station method, a source-station is excluded if the length
 351 of either $C_2^{CW}(s_k, r_i)$ or $C_2^{CW}(s_k, r_j)$ is less than 1500 s, which is needed to include sig-
 352 nals for the longest station pairs (> 3000 km).

353 3.3 Estimating Composite Green’s Functions

354 To compute the composite Green’s function, $\hat{G}(r_i, r_j)$, for each of the three-station
 355 methods we apply the weighted sum given by eq. (1) based on the stacking weights (sec-
 356 tion 3.2). **Fig. 6** provides some examples using the same pair of receiver-stations used
 357 in the record-sections of **Fig. 5**. **Fig. 6a** presents an example composite Green’s func-
 358 tion for three-station coda-wave interferometry (\mathcal{I}_3^{CW}). For this method, no stationary
 359 phase zone is needed, so contributions from all source-stations are included in the stack.
 360 This is the black line in **Fig. 6a**, labelled “stack all”, which is compared to the two-station
 361 ambient noise cross-correlation plotted as the red line and labelled \mathcal{I}_2^{AN} . Two observa-
 362 tions of noteworthy: First, one of the features of coda-wave interferometry is the ten-

363 dependency for the composite Green’s functions to be more symmetric than for two-station
 364 ambient noise methods (e.g., Stehly et al., 2008, and many others), and this is also ob-
 365 served in this example. We found it, however, to be an artifact due to the use of sym-
 366 metric components (Sheng et al., 2018). Second, the SNR of the three-station coda-wave
 367 composite Green’s function is lower than for the two-station record, even though in this
 368 case 514 source-stations contribute to the three-station interferogram. This highlights
 369 another aspect of coda-wave interferometry, i.e., signals emerge from noise very slowly
 370 as source-stations are introduced. And, as can be seen in **Fig. 5a**, constituent source-
 371 specific three-station interferograms are typically very noisy so that signals cannot be
 372 discerned in any of them. The implication is that coda-wave interferometry can play a
 373 useful role in ambient noise interferometry only in the presence of many long duration
 374 source-stations, unless more sophisticated data processing procedures are applied (**section**
 375 **6.2**). For comparison, we also plot in **Fig. 6a** the recovered composite Green’s function
 376 based on source-stations that lie exclusively in the hyperbolic stationary phase zone. The
 377 choice of source-stations in this zone further degrades the SNR of the composite Green’s
 378 function, indicating that there is no geometrical advantage to choosing source-stations
 379 in the end-fire directions in coda-wave interferometry.

380 **Fig. 6b** shows an example composite Green’s function for three-station direct-wave
 381 interferometry where the source-stations lie in the hyperbolic stationary phase zone ($^{hyp}\mathcal{I}_3^{DW}$).
 382 In this case, the green line, which is the stack for source-stations only in the hyperbolic
 383 stationary phase zones (labelled “stack in hyp”), is the Green’s function estimate, and
 384 there are 26 source-stations. Retaining source-stations at all azimuths (black line) de-
 385 grades the result by adding precursory noise. Two comments are worthy of note in com-
 386 paring the three-station composite Green’s function (green line) with two-station Green’s
 387 function (red line). First, the relative amplitudes for the different correlation lags are
 388 more similar than for coda-waves. Second, precursory noise is lower for the three-station
 389 estimate. These are both common characteristics when comparing two-station to three-
 390 station Green’s functions.

391 Finally, **Fig. 6c** presents an example composite Green’s function for three-station
 392 direct-wave interferometry where the source-stations lie in the elliptical stationary phase
 393 zone ($^{ell}\mathcal{I}_3^{DW}$). The green line, which is the stack for source-stations only in the ellip-
 394 tical stationary phase zones (labelled “stack in ellipse”), is the composite Green’s func-
 395 tion estimate, and there are 7 source-stations. As with the hyperbolic stationary phase

396 zone, retaining source-stations at all azimuths (black line) degrades the result but in this
 397 case adds both precursory and trailing noise, especially the latter. In this case, too, there
 398 is lower precursory noise for the three-station estimate than for \mathcal{I}_2^{AN} .

399 4 Dispersion Measurements

400 As part of dispersion measurement, we apply two additional quality control crite-
 401 ria. First, for a dispersion measurement to be retained, we apply a spectral SNR (Bensen
 402 et al., 2007) criterion to the composite Green’s function, where again SNR is defined as
 403 the peak amplitude in the direct-wave window divided by the rms of the waveform in
 404 the coda-wave window. That is, at a given period the SNR of the composite Green’s func-
 405 tion must be ≥ 10 or else the dispersion measurement at that period is discarded. Sec-
 406 ond, for the dispersion measurement to be retained, the distance between the two receiver-
 407 stations must be greater than one wavelength. For example, if the phase speed is 3.5 km/s,
 408 at 20 s period the receiver-stations must be separated by more than 70 km. This crite-
 409 rion becomes more restrictive as period increases. We do not, however, apply the one-
 410 wavelength criterion to the two source-receiver cross-correlations.

411 To measure frequency dependent phase speed, we apply frequency-time analysis
 412 (FTAN; Dziewonski et al., 1969; Levshin & Ritzwoller, 2001; Bensen et al., 2007). We
 413 assume that the measured phase of a seismogram at frequency ω in the frequency do-
 414 main for receiver-stations r_i and r_j is approximately (Lin et al., 2008)

$$\phi_{ij}(\omega) = \frac{\omega}{c_{ij}} d_{ij} + \frac{\pi}{4} + 2N\pi + \phi_s, \quad N \in \mathbb{Z}, \quad (6)$$

415 where d_{ij} is the distance between the two receiver-stations, $\pi/4$ is from the far-field or
 416 high-frequency asymptotic approximation of the Bessel function, ϕ_s is an initial phase
 417 term, and c_{ij} is the frequency-dependent phase speed, which is what we aim to measure.
 418 A key assumption here is that we use the inter-receiver-station distance in eq. (6). This
 419 assumption leads to a biased measurement for the three-station direct-wave methods,
 420 and the nature of this bias and its correction is discussed in **sections 5.3** and **6.1**.

421 For two-station ambient noise interferometry, \mathcal{I}_2 , $\phi_s \approx 0$ has been shown theo-
 422 retically (e.g., Snieder, 2004) and empirically (e.g., Yao et al., 2006; Lin et al., 2008). For
 423 three-station coda-wave interferometry, \mathcal{I}_3^{CW} , ϕ_s should also be approximately 0. How-
 424 ever, for three-station direct-wave interferometry, \mathcal{I}_3^{DW} , ϕ_s will differ from 0, and this
 425 initial phase must be taken into account when measuring phase speed. Because corre-

426 lation or convolution of two composite Green’s functions will determine the difference
 427 or sum of the phases in the frequency domain, respectively:

$$\phi_s \approx \begin{cases} \frac{\pi}{4} & \text{for } \mathcal{I}_3^{DW}, \\ -\frac{\pi}{4} & \text{for } \mathcal{I}_3^{hypDW}. \end{cases} \quad (7)$$

428 The use of these values of ϕ_s for \mathcal{I}_3^{DW} is tested in **section 5**.

429 **Fig. 7** compares example frequency-time (FTAN) diagrams for the two-station method
 430 and the three-station methods, for the two receiver-stations M07A and M15A. The four
 431 diagrams are similar but the diagrams for the two direct-wave methods show larger rel-
 432 ative amplitudes at longer periods and the coda-wave diagram has group speeds that in-
 433 crease non-physically at longer periods. A detailed comparison of the dispersion mea-
 434 surements that emerge from the various methods is presented in **section 5.2**.

435 5 Results

436 To validate and compare the three-station methods we report results from the raw
 437 dispersion measurements and from surface wave tomography based on them. To perform
 438 tomography, we apply the eikonal tomography method (e.g., [Lin et al., 2009](#)) to Rayleigh
 439 wave phase speed measurements obtained from the two-station and three-station meth-
 440 ods. We employ the eikonal tomography method rather than traditional tomographic
 441 methods that minimize a penalty functional (e.g., [Barmin et al., 2001](#)) because eikonal
 442 tomography applies no ad-hoc regularization that depends on data coverage. This sim-
 443 plifies comparison of results from different datasets because they are less affected by dif-
 444 ferences in the number and distribution of wave paths.

445 5.1 General Characteristics of \mathcal{I}_3 Measurements

446 **Fig. 8a** summarizes the spectral signal-to-noise ratio (SNR) of each of the four in-
 447 terferometric methods, averaging over the entire data set of dispersion measurements.
 448 Generally speaking, SNR decreases with period and the trends are similar between \mathcal{I}_3
 449 and \mathcal{I}_2^{AN} . The peak near 20 s periods corresponds to the primary microseism, while the
 450 dip near 26 s period corresponds to the existence of a spatially localized microseismic
 451 source (e.g., [Shapiro et al., 2006](#)). **Fig. 8b** presents the SNR results relative to the SNR
 452 for \mathcal{I}_2^{AN} . The SNR for \mathcal{I}_3^{DW} is slightly larger than for \mathcal{I}_3^{hypDW} , while both have a SNR

453 more than twice that of \mathcal{I}_2^{AN} across a broad bandwidth. In contrast, \mathcal{I}_3^{CW} has a much
 454 lower median SNR (< 10) across all periods.

455 Because SNR plays the most significant role in the quality control of dispersion mea-
 456 surements, the number of accepted \mathcal{I}_2 and \mathcal{I}_3 measurements varies with period similar
 457 to SNR (**Fig. 9a**). The number of accepted \mathcal{I}_3 measurements can be divided into three
 458 categories depending on whether the two receiver-stations operated at the same time (syn-
 459 chronously) and whether an \mathcal{I}_2 measurement exists for the path so that the \mathcal{I}_3 measure-
 460 ment is new or repeated. These three categories of \mathcal{I}_3 measurements are referred to as
 461 “Synchronous-Repeated” (receiver-stations deployed synchronously, with both an \mathcal{I}_3 and
 462 an \mathcal{I}_2 measurement), “Synchronous-New” (receiver-stations deployed synchronously, with
 463 an \mathcal{I}_3 but not an \mathcal{I}_2 measurement), and “Asynchronous-New” (receiver-stations deployed
 464 asynchronously, with only an \mathcal{I}_3 measurement). In the Synchronous-New case, the receiver-
 465 stations produced an \mathcal{I}_2 measurement but it was rejected, usually because it did not meet
 466 the SNR requirement. The numbers of \mathcal{I}_3 measurements that derive from these three
 467 categories are shown in **Fig. 9b-d**. In all categories, $^{ell}\mathcal{I}_3^{DW}$ measurements somewhat
 468 outnumber the $^{hyp}\mathcal{I}_3^{DW}$ measurements, and both outnumber the \mathcal{I}_2^{AN} measurements (in
 469 cases where they exist) and greatly outnumber the \mathcal{I}_3^{CW} measurements.

470 **Fig. 9b** is for the Synchronous-Repeated category of \mathcal{I}_3 measurements. By def-
 471 inition, the number of \mathcal{I}_3 measurements will be no larger than the number of \mathcal{I}_2 mea-
 472 surements. Nearly every existing \mathcal{I}_2^{AN} measurement is accompanied by an \mathcal{I}_3^{DW} mea-
 473 surement, but the number of \mathcal{I}_3^{CW} measurements is considerably smaller. The number
 474 of these measurements generally decreases with period after maximizing between 20 and
 475 30 s, although the \mathcal{I}_3^{CW} measurement maximizes nearer to 15 s period and decays very
 476 rapidly at longer periods.

477 **Fig. 9c** is for the Synchronous-New category of \mathcal{I}_3 measurements, and illustrates
 478 that many new longer periods measurements emerge from the \mathcal{I}_3^{DW} method. Above about
 479 50 s period, \mathcal{I}_3^{DW} nearly doubles the number of measurements between synchronously
 480 deployed stations. Although a principal attraction of the three-station methods is the
 481 ability to obtain measurements between asynchronously deployed stations, but many new
 482 measurements result from the \mathcal{I}_3^{DW} methods even for synchronously deployed stations
 483 particularly at long periods. There are essentially no new measurements from \mathcal{I}_3^{CW} in
 484 this category.

485 **Fig. 9d** is for the Aynchronous-New category of \mathcal{I}_3 measurements, measurements
 486 from the \mathcal{I}_3 methods that are inherently non-existent for \mathcal{I}_2 . Relative to the number
 487 of measurements delivered by \mathcal{I}_2^{AN} , the greatest impact of the \mathcal{I}_3 methods is at the longer
 488 periods of the bandwidth considered. The vast majority of the measurements for \mathcal{I}_3^{CW}
 489 are from synchronously deployed stations (**Fig. 9b**), indicating that it is difficult for \mathcal{I}_3^{CW}
 490 to bridge asynchronous stations.

491 5.2 Phase Speed Measurements from Three-Station (\mathcal{I}_3) vs. Two-Station 492 (\mathcal{I}_2) Interferometry

493 **Fig. 10** and **Table 1** present comparisons of Rayleigh wave phase speed measure-
 494 ments derived from the three-station methods to two-station interferometry for common
 495 receiver-station pairs. Let $\hat{G}_3(r_i, r_j)$ be a composite three-station Green's function be-
 496 tween receiver-stations r_i and r_j , and $\hat{G}_2(r_i, r_j)$ be the two-station estimate of the Green's
 497 function between the same two stations, where the time-dependence is suppressed in this
 498 notation. **Fig. 10** and **Table 1** present the mean and standard deviation of the differ-
 499 ence between $\hat{G}_3(r_i, r_j)$ and $\hat{G}_2(r_i, r_j)$ computed over all common receiver-station pairs
 500 for each of the three-station methods.

501 **Fig. 10a** and **Table 1** (column 2) show that the mean difference between the two-
 502 station Green's functions and the three-station composite Green's functions based on coda-
 503 waves is negligible (< 1 m/s, on average), from which we infer that the three-station method
 504 based on coda-waves is unbiased. The standard deviation of the difference grows with
 505 period, but is small (< 15 m/s) at all periods, although results extend only up to 22 s
 506 period.

507 In contrast, **Fig. 10b,c** and **Table 1** (columns 4 & 6) show the existence of a non-
 508 zero systematic difference or bias between each of the three-station direct-wave meth-
 509 ods and two station interferometry. For $^{ell}\mathcal{I}_3^{DW}$, the absolute amplitude of the bias gener-
 510 ally increases with period (from less than 10 m/s at 10 s to nearly 20 m/s at 80 s). For
 511 $^{hyp}\mathcal{I}_3^{DW}$, the absolute amplitude of the bias increases with a similar trend until 40 s, but
 512 then decreases rapidly (to only 1 m/s at 80 s). For the reasons discussed in **section 6.1**,
 513 $^{ell}\mathcal{I}_3^{DW}$ is biased slow relative to \mathcal{I}_2^{AN} (the difference in **Fig. 10b** is negative on aver-
 514 age) and $^{hyp}\mathcal{I}_3^{DW}$ is biased fast (the difference in **Fig. 10c** is positive on average). We
 515 also discuss in **section 6.1** a ray-theoretic approach to reducing this bias.

516 In contrast with the bias, the standard deviations of the differences between the
 517 dispersion measurements from the \mathcal{I}_2^{AN} method to both \mathcal{I}_3^{DW} methods grow with pe-
 518 riod, as **Fig. 10b,c** and **Table 1 (columns 5 & 7)** show, particularly above 40 s pe-
 519 riod. Partly, this is due to the decrease in signal-to-noise ratio (SNR) in both the three-
 520 station and two-station Green’s functions at longer periods (**Fig. 9a**). However, irre-
 521 spective of SNR, we do not expect the dispersion measurements from the three-station
 522 methods to agree with those from the two-station method as well at longer periods. The
 523 reason is that the Fresnel Zone or sensitivity kernel for the three-station methods is not
 524 identical to the sensitivity kernel for the two-station method and the differences in sen-
 525 sitivity grow with period.

526 **Fig. 11** schematically illustrates the difference in sensitivity for the three-station
 527 direct-wave measurements and the two-station measurement, in which we approximate
 528 the Fresnel Zone for the two-station method as an ellipse, shown with dashed lines, with
 529 the two receiver-stations at the ellipse’s foci. The Fresnel Zone for the method $^{ell}\mathcal{I}_3^{DW}$
 530 is approximately the sum of the two Fresnel zones for each of the constituent waves that
 531 emanate from the source-station (red dot in **Fig. 11a**) which lies between the receiver-
 532 stations for this method. The sensitivity zone for $^{ell}\mathcal{I}_3^{DW}$ is smaller than for \mathcal{I}_2 , on av-
 533 erage, and we therefore expect that the method $^{ell}\mathcal{I}_3^{DW}$ will have a higher resolution than
 534 \mathcal{I}_2 , everything else being equal. In contrast, the Fresnel Zone for the method $^{hyp}\mathcal{I}_3^{DW}$
 535 is approximately the difference of the two Fresnel zones for each of the constituent waves
 536 that emanate from the source-stations (red dots in **Fig. 11b**), which lie outside the receiver-
 537 stations. This sensitivity zone for $^{hyp}\mathcal{I}_3^{DW}$ is larger and considerably more complicated
 538 than for \mathcal{I}_2 , on average. We, therefore, expect that the method $^{hyp}\mathcal{I}_3^{DW}$ will have a lower
 539 resolution than \mathcal{I}_2 , everything else being equal.

540 The Fresnel zones for the \mathcal{I}_2^{AN} method widen with period, as will those for the \mathcal{I}_3^{DW}
 541 methods. Therefore, differences between the Fresnel zones of the \mathcal{I}_3^{DW} methods compared
 542 with the Fresnel zone of the \mathcal{I}_2^{AN} method will increase with period, too, as the various
 543 methods sample the earth between and around the pair of receiver-stations increasingly
 544 differently. We believe this is the source of the increase in the standard deviations of the
 545 differences between the phase speed measurements for the various methods, as shown
 546 in **Fig. 10** and **Table 1**.

547 The analysis of Fresnel Zones presented here is schematic and illustrative. The Fresnel
 548 Zones have internal structure that will produce details in the sums and differences
 549 presented in **Fig. 11**. General conclusions about the nature of the differences between
 550 the various Fresnel Zones are robust, but to use this information quantitatively to im-
 551 prove images in the future will require much more careful computation of the Fresnel zones
 552 (e.g., [de Vos et al., 2013](#); [Fichtner et al., 2017](#)).

553 **5.3 Tomography Based on Three-Station (\mathcal{I}_3) vs. Two-Station (\mathcal{I}_2) In-** 554 **terferometry**

555 The Rayleigh wave phase speed maps produced by the three-station (\mathcal{I}_3) and two-
 556 station (\mathcal{I}_2^{AN}) methods are generally quite similar, as displayed at periods of 10 s, 20 s,
 557 40 s, and 60 s in **Figs 12 - 14**. The touchstone is the two-station map (\mathcal{I}_2^{AN}), and at
 558 each period there is substantial agreement between the \mathcal{I}_3 maps with the \mathcal{I}_2^{AN} map. How-
 559 ever, we do not show the three-station coda-wave (\mathcal{I}_3^{CW}) maps at periods of 40 s and
 560 60 s because the method does not provide enough measurements to perform tomogra-
 561 phy reliably at periods above 25 s. Presumably, this is because the coda is enriched at
 562 the shorter periods. The number of measurements produce by each of the three-station
 563 methods is discussed in greater detail in **section 5.1**.

564 A more careful comparison of the tomographic maps requires detailed inspection
 565 of the differences between the maps. Let us assume that we have two dispersion maps
 566 on the same grid of longitudes (x_i) and latitudes (y_j): $c_{ij}^{(1)} = c^{(1)}(x_i, y_j)$ and $c_{ij}^{(2)} =$
 567 $c^{(2)}(x_i, y_j)$. Let Δ_{ij} be the difference between these maps:

$$\Delta_{ij} = c_{ij}^{(1)} - c_{ij}^{(2)}, \quad (8)$$

568 whose mean over (x_i, y_j) is denoted as $\bar{\Delta}$ and standard deviation as σ_{Δ} . **Figs 15 - 16**
 569 display such differences between the three-station methods with two-station interferom-
 570 etry in map form and **Table 2** summarizes the differences, tabulating $\bar{\Delta}$ and σ_{Δ} .

571 **Fig. 15** (and **Table 2**, column 2) shows the difference between the Rayleigh wave
 572 phase speed maps at periods of 10 s and 20 s from three-station coda-wave interferom-
 573 etry (\mathcal{I}_3^{CW}) and two-station interferometry (\mathcal{I}_2^{AN}). There is essentially no systematic dif-
 574 ference between the maps ($|\bar{\Delta}| < 1$ m/s) and the standard deviation of the differences
 575 is also small ($\sigma_{\Delta} < 8$ m/s). Unfortunately, we are unable to produce meaningful to-

576 tomographic maps from \mathcal{I}_3^{CW} at longer periods, while it may be more feasible to push \mathcal{I}_3^{CW}
 577 towards shorter periods (**section 6.2**).

578 **Fig. 16** presents difference maps at periods from 10 s to 60 s for the two three-
 579 station direct-wave methods ($^{ell}\mathcal{I}_3^{DW}$ and $^{hyp}\mathcal{I}_3^{DW}$) relative to \mathcal{I}_2^{AN} . **Table 2**, columns
 580 4-7, summarizes the mean and standard deviation of the difference over the maps. Both
 581 methods result in a systematic bias compared to \mathcal{I}_2^{AN} , albeit with different signs and the
 582 bias for $^{ell}\mathcal{I}_3^{DW}$ is larger than for $^{hyp}\mathcal{I}_3^{DW}$. In addition, the standard deviation of the dif-
 583 ferences generally grow with period. These results are similar to the bias and standard
 584 deviation in the raw phase speed measurements for the two methods (**Fig. 10** and **Ta-**
 585 **ble 1**). The methods produce systematic errors (or bias) for reasons that are discussed
 586 in **section 6.1**. The standard deviations of the differences grow with period because the
 587 \mathcal{I}_3^{DW} methods increasingly sample the earth differently than the (\mathcal{I}_2^{AN}) method at longer
 588 periods (**section 5.2**).

589 6 Discussion

590 We have focused assessment of the three-station methods on the consistency be-
 591 tween Rayleigh wave phase speed measurements and maps (tomograms) that derive from
 592 the various methods from 10 s to 60 s period (e.g., **Figs 12 - 14**). As shown, the phase
 593 speed measurements and the tomographic maps from the \mathcal{I}_3 methods are generally con-
 594 sistent with those from \mathcal{I}_2^{AN} . The three-station method based on coda-waves (\mathcal{I}_3^{CW}) has
 595 a much lower SNR than the direct-wave three-station methods as well as two-station in-
 596 terferometry, and produces sufficient measurements for tomography only at shorter pe-
 597 riods (< 25 s). In contrast, the three-station direct-wave methods (\mathcal{I}_3^{DW}) have a SNR
 598 two to three times larger than two-station interferometry (\mathcal{I}_2^{AN}), on average. Combin-
 599 ing this with the bridging of asynchronous stations to provide new inter-station paths
 600 for tomography, there is as much as a factor of two enhancement relative to two-station
 601 interferometry in the number of paths across a broad frequency band. This enhancement
 602 is most prominent at longer periods (>40 s).

603 The direct-wave three-stations methods, however, possess a systematic bias rela-
 604 tive to the \mathcal{I}_2^{AN} method. The practitioner of these methods must determine whether the
 605 extent of the bias is significant for the applications of interest. For applications in which
 606 the bias is problematic, we show in **section 6.1** that the bias can be estimated and ac-

607 counted for approximately with a ray-theoretic de-biasing adjustment to the dispersion
 608 measurements that is effective in the period range where ray-theory is accurate. **Sec-**
 609 **tion 6.2** discusses other variants of the methods presented here that may provide fruit-
 610 ful directions for future improvement.

611 **6.1 Correcting the Bias in Three-Station Direct-Wave Interferometry** 612 (\mathcal{I}_3^{DW})

613 As described above, the three-station methods are based on measuring the phase
 614 speed of the composite Green's function (equation (1)), $\hat{G}(r_i, r_j)$, between a pair of receiver-
 615 stations (r_i, r_j) , which is a stack of source-specific interferograms, $C_3(r_i, r_j; s_k)$, that emerge
 616 from particular source-stations s_k . The phase speed, c_{ij} , is measured using the compos-
 617 ite Green's function based on eq. (6) under the assumption that the appropriate prop-
 618 agation distance is d_{ij} , the great-circle distance between r_i and r_j . It is this assumption
 619 of d_{ij} for the composite Green's function that produces the systematic bias in the three-
 620 station direct-wave methods.

621 The physical cause of the bias of the three-station direct-wave methods is geomet-
 622 rical and can be understood ray theoretically (**Fig. 17**). For the direct-wave method based
 623 on an elliptical stationary phase zone, $^{ell}\mathcal{I}_3^{DW}$, the source-station s_k lies generally be-
 624 tween the two receiver-stations at distances d_{ki} from r_i and d_{kj} from r_j (**Fig. 17a**). The
 625 actual distance the rays will travel for the method $^{ell}\mathcal{I}_3^{DW}$ based on source s_k is the sum
 626 of the constituent ray paths:

$$^{ell}d'_{ij} = d_{ki} + d_{kj} \geq d_{ij}. \quad (9)$$

627 Because $^{ell}d'_{ij}$ is longer than the inter-receiver-station distance, assuming the distance
 628 traveled is d_{ij} will result in a phase speed that is biased slow. Similarly, for the three-
 629 station direct-wave method, $^{hyp}\mathcal{I}_3^{DW}$, sources lie generally outside the two receiver-stations
 630 (**Fig. 17b**). The actual distance the rays will travel for the method $^{hyp}\mathcal{I}_3^{DW}$ based on
 631 source s_k is the difference in the constituent ray paths:

$$^{hyp}d'_{ij} = d_{ki} - d_{kj} \leq d_{ij}. \quad (10)$$

632 Because $^{hyp}d'_{ij}$ is shorter than the inter-receiver-station distance, the assumption that
 633 distance traveled is d_{ij} will result in a phase speed that is biased fast.

634 Therefore, the correct distance to be used in measuring phase speed will depend
 635 on the specific location of each source-station. The use of the composite Green’s func-
 636 tion invariably will yield a biased phase speed measurement unless the phase of the con-
 637 stituent source-specific interferograms are shifted prior to stacking (**section 6.2**) or if
 638 the composite Green’s function is abandoned and corrections are applied to dispersion
 639 curves measured on the source-specific interferograms. Here, we report on the effect of
 640 the latter correction. To “de-bias” the phase speed measurements, we abandon the com-
 641 posite Green’s function and measure a phase speed curve for each source-specific inter-
 642 ferogram ($C_3(r_i, r_j; s_k)$) independently based on the more accurate ray-theoretic distance,
 643 $^{ell}d'_{ij}$ or $^{hyp}d'_{ij}$, and then average the resulting phase speed curves.

644 **Fig. 18** presents an example of the set of source-specific phase speed curves that
 645 have been de-biased by using the source-specific ray-theoretic distances for receiver-stations
 646 M07A and M15A. Grey curves are individual Rayleigh wave phase speed measurements
 647 for individual source-specific interferograms, of which there are seven for $^{ell}\mathcal{I}_3^{DW}$ (**Fig.**
 648 **18a**) and 26 for $^{hyp}\mathcal{I}_3^{DW}$ (**Fig. 18b**). Black lines and error bars indicate the mean and
 649 standard deviation (σ) of the source-specific curves. At each period we reject a source-
 650 specific measurement if it lies more than 2σ from the mean and we discard the mean mea-
 651 surement altogether if $\sigma > 60$ m/s, which occurs in the example of **Fig. 18** at peri-
 652 ods greater than 40 s. **Fig. 19a** shows the mean correction applied across the entire data
 653 set for the two three-station direct-wave methods. The average standard deviation amongst
 654 the constituent source-specific curves over the entire data set is presented in **Fig. 19b**.
 655 The standard deviations for the $^{ell}\mathcal{I}_3^{DW}$ method are generally smaller than the $^{ell}\mathcal{I}_3^{DW}$
 656 method, consistent with the latter having larger and more complex sensitivity zones (**section**
 657 **5.2**). These standard deviations could serve as uncertainty estimates for the resulting
 658 dispersion measurements.

659 After the de-biasing correction, the mean and standard deviation of the difference
 660 between the \mathcal{I}_3^{DW} and \mathcal{I}_2^{AN} measurements are listed in **Table 3**, which should be con-
 661 trasted with **Table 1** that contains the same statistics without the de-biasing. The cor-
 662 rection has little effect on the standard deviation, but the mean difference between the
 663 \mathcal{I}_3^{DW} and \mathcal{I}_2^{AN} measurements decreases in all periods, except for $^{hyp}\mathcal{I}_3^{DW}$ at 80 s. If we
 664 consider the mean difference to be a measure of residual bias, then the bias of the cor-
 665 rected measurements is small up through 50 s period (< 7 m/s) for both three-station
 666 methods. However, it grows at longer periods for the $^{ell}\mathcal{I}_3^{DW}$ method up to ~ 15 m/s,

667 presumably because the ray-theoretic correction becomes less effective at longer periods.
 668 For reasons we do not fully understand, the $hyp\mathcal{I}_3^{DW}$ method has a smaller residual bias
 669 than the $ell\mathcal{I}_3^{DW}$ method, although the standard deviations of the differences tends to
 670 be larger. This information is presented in **Fig. 20** at all periods for comparison with
 671 **Fig. 10**.

672 6.2 Potential for Further Refinements

673 We have chosen many of the characteristics of the two-station and three-station
 674 interferometric methods in a reasoned but largely ad-hoc way. Thus, all of the proce-
 675 dures we describe here may be refined to improve some aspect of the results. Such re-
 676 finements could be made (1) to the data processing procedures, (2) to the definition of
 677 the stationary phase zones for the direct-wave methods, (3) to the de-biasing procedure
 678 applied to the direct-wave methods, and (4) to the use of the results from the different
 679 methods in concert with one another. Finally, (5) the three-station direct-wave meth-
 680 ods could work optimally for new generalized interferometric methods based on not es-
 681 timating Green’s functions.

682 (1) Data processing procedures include the definition of both the direct-wave and
 683 coda-wave windows, the one-wavelength criterion for the minimum inter-receiver-station
 684 distance, the chosen values of the stacking weights w_j , and the use of only of the sym-
 685 metric component of the two-station ambient noise interferograms as the basis for all of
 686 data processing. In addition, the two-station data processing procedures of [Shen and Ritz-](#)
 687 [woller \(2016\)](#) underlie our results, including the use of an 80 s moving average time-domain
 688 normalization window and spectral whitening. All of these choices may be revised in the
 689 future to optimize the result of data processing. In particular, the stacking weights could
 690 incorporate information about the spatial distribution of source-stations ([Entwistle et](#)
 691 [al., 2015](#)). For three station coda-wave interferometry (\mathcal{I}_3^{CW}), performing interferom-
 692 etry on pre-stacked \mathcal{I}_2 ([Zhang & Yang, 2013](#); [Haendel et al., 2016](#)) may greatly increase
 693 SNR because cross-talks between incoherent signals are avoided ([Sheng et al., 2018](#)). De-
 694 spite its inapplicability to asynchronous pairs, this pre-stacking scheme may be promis-
 695 ing for extraction of short-period (< 5 s) information ([Sheng et al., 2018](#)).

696 (2) Another important characteristic of the three-station direct-wave methods is
 697 the definition of the stationary-phase zones. We choose $\alpha = 10^{-2}$ to be period-independent,

698 which produces a maximum angle of both the elliptical and hyperbolic stationary phase
 699 zones of about $\theta = 8^\circ$. An optimal period-dependent parameterization of the station-
 700 ary phase zones may be possible. Moreover, because increasing α should increase the bias
 701 of the three-station methods, in station-rich settings α may be reduced and in station-
 702 poor regions it may be increased, although at the expense of increasing bias.

703 (3) The de-biasing method outlined in **section 6.1** applies corrections to disper-
 704 sion curves before they are statistically summarized for each path, based on a great-circle
 705 ray-theoretic procedure. This method could be improved by correcting additional errors
 706 from off-great-circle propagation (e.g., Yao et al., 2006; Foster et al., 2014), non-plane
 707 waves (e.g., Pedersen, 2006) and finite-frequency effects (e.g., Yao et al., 2010; de Vos
 708 et al., 2013; Fichtner et al., 2017). Alternately, a completely different approach may be
 709 possible, which applies phase corrections to source-specific interferograms (C^3) and then
 710 makes the dispersion measurements on the composite Green’s function (\hat{G}_3). The cor-
 711 rection is a (frequency-dependent) phase shift to each of the source-specific interferograms
 712 prior to stacking.

713 (4) Because the three-station methods (\mathcal{I}_3) are consistent with the two-station method
 714 (\mathcal{I}_2), measurements from all methods can be combined simultaneously. It might be par-
 715 ticularly advantageous to combine measurements from methods $^{ell}\mathcal{I}_3^{DW}$ and $^{hyp}\mathcal{I}_3^{DW}$ be-
 716 cause they are oppositely biased, and their biases may cancel approximately without an
 717 explicit bias correction.

718 (5) New methods of interferometry are being developed that are not dependent on
 719 estimating Green’s functions, but rather attempt to extract information about the prop-
 720 agating medium irrespective of the relative position of the sources and receiver-stations
 721 (e.g., Fichtner et al., 2017). Three-station direct-wave interferometry, where the loca-
 722 tion of source-stations is known exactly, may provide an ideal application for these meth-
 723 ods.

724 7 Conclusions

725 Our principal finding is that the three-station direct-wave interferometry methods
 726 $^{ell}\mathcal{I}_3^{DW}$ and $^{hyp}\mathcal{I}_3^{DW}$ generally outperform three-station coda-wave interferometry \mathcal{I}_3^{CW} ,
 727 even though direct-wave interferometry has been largely ignored as an imaging tool to
 728 date. This outperformance includes such metrics as signal-to-noise ratio, the number of

729 measurements returned, and most notably the band-width of the measurements because
 730 \mathcal{I}_3^{CW} is primarily confined to providing measurements below 25 s period. In addition,
 731 the direct-wave methods also outperform two-station interferometry in these metrics.

732 There are two primary caveats concerning the performance of the three-station direct-
 733 wave methods. First, the $ell\mathcal{I}_3^{DW}$ and $hyp\mathcal{I}_3^{DW}$ methods are slightly biased relative to two-
 734 station interferometry, \mathcal{I}_2^{AN} . However, we present a ray-theoretic de-biasing procedure
 735 that nearly eliminates the bias at and below about 50 s period, where ray-theory is ex-
 736 pected to work best, and substantially reduces bias at longer periods. Second, the sen-
 737 sitivity kernels for the three-station direct-wave methods are more complicated than both
 738 two-station interferometry and three-station coda-wave interferometry and remain poorly
 739 understood. Research is needed to understand the nature of the sensitivity kernels for
 740 the three-station direct-wave methods and how they compare to two-station interferom-
 741 etry.

742 The results in this paper may be considered to provide proofs-of-concept based on
 743 a set of reasoned, but ad-hoc choices in developing the three-station methods. These meth-
 744 ods may be improved by further refinements and optimization. A prominent example
 745 is how we perform the bias correction for the three-station direct-wave methods. An al-
 746 ternative procedure would be to phase-shift individual three-station source-specific in-
 747 terferograms prior to stacking, which may perform better than the de-biasing method
 748 we present here.

749 The tests presented here use data from the EarthScope Transportable Array (TA),
 750 but the relative merits of the various methods tested may vary in different settings where
 751 station coverage and geometries will differ. Indeed, the three-station methods that we
 752 test here may be least needed in the contiguous US due to the outstanding data cover-
 753 age provided by the TA. Tests in different regions (e.g., Antarctica, Tibet, Europe, Alaska,
 754 the Juan de Fuca Plate, etc.) are needed to determine how the methods will perform in
 755 a variety of settings.

756 Irrespective of these caveats, we believe that three-station direct-wave interferom-
 757 etry promises to provide a substantial new tool to the toolbox of standard methods for
 758 imaging the structure of the crust and uppermost mantle. We encourage seismologists
 759 to bear in mind its ability to bridge asynchronously deployed stations in designing new
 760 seismic networks.

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Table 1. Differences (m/s) of Rayleigh wave phase speed measurements from the \mathcal{I}_3 methods compared to \mathcal{I}_2 before de-biasing correction

Period (s)	\mathcal{I}_3^{CW}		$ell\mathcal{I}_3^{DW}$		$hyp\mathcal{I}_3^{DW}$	
	Mean	SD	Mean	SD	Mean	SD
10	-0.2	3.9	-9.8	4.8	10.7	5.7
20	0.9	12.5	-11.6	6.4	13.4	8.0
30	-	-	-12.5	10.9	14.4	13.2
40	-	-	-10.9	17.5	13.2	20.7
50	-	-	-13.9	23.8	11.8	27.1
60	-	-	-17.0	28.2	9.2	31.4
70	-	-	-18.7	30.2	5.1	34.5
80	-	-	-17.2	31.1	1.2	36.5

Table 2. Differences (m/s) of Rayleigh wave phase speed maps from the \mathcal{I}_3 methods compared to \mathcal{I}_2

Period (s)	\mathcal{I}_3^{CW}		$ell\mathcal{I}_3^{DW}$		$hyp\mathcal{I}_3^{DW}$	
	Mean	SD	Mean	SD	Mean	SD
10	0.7	4.6	-8.4	4.3	7.5	4.3
20	-0.6	7.6	-12.5	4.0	9.9	3.9
30	-	-	-20.6	6.1	7.8	6.2
40	-	-	-29.3	11.3	3.1	10.2
50	-	-	-33.9	17.6	0.1	16.5
60	-	-	-39.8	25.0	-5.0	22.2

Table 3. Differences (m/s) of Rayleigh wave phase speed measurements from the direct-wave \mathcal{I}_3 methods compared to \mathcal{I}_2 after de-biasing correction

Period (s)	$ell\mathcal{I}_3^{DW}$		$hyp\mathcal{I}_3^{DW}$	
	Mean	SD	Mean	SD
10	-0.0	5.5	0.1	7.8
20	1.1	7.2	0.0	9.3
30	0.5	11.5	-1.1	15.3
40	-2.3	17.7	1.8	23.7
50	-6.5	24.2	6.0	29.3
60	-10.0	28.0	7.0	31.6
70	-13.3	28.4	4.8	32.6
80	-15.1	27.4	1.9	33.0

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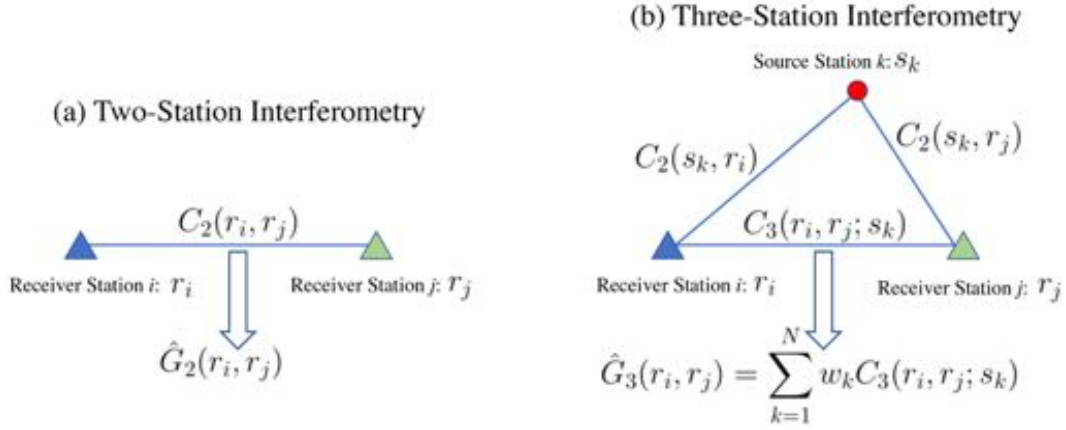
Figures:

Figure 1. Notation for interferometry. (a) Two-station interferometry. $C_2(r_i, r_j)$ is the cross-correlation between processed seismograms recorded at receiver-stations r_i and r_j . The two-station estimated Green's function, $\hat{G}_2(r_i, r_j)$, can be determined from C_2 after applying an appropriate phase shift. Receiver-stations r_i and r_j must operate synchronously. (b) Three-station interferometry. Cross-correlations between seismograms recorded at each source-station, s_k , with records at receiver-stations, r_i and r_j , are denoted $C_2(s_k, r_i)$ and $C_2(s_k, r_j)$. Direct-wave or coda-wave parts of these records are cross-correlated or convolved to measure the source-specific interferogram, $C_3(r_i, r_j; s_k)$, which can be summed over contributions from many source-stations to produce the three-station composite Green's function, $\hat{G}_3(r_i, r_j)$, between the receiver-stations. Receiver-stations r_i and r_j need not operate synchronously with one another, but both must overlap the operation of each source-station.

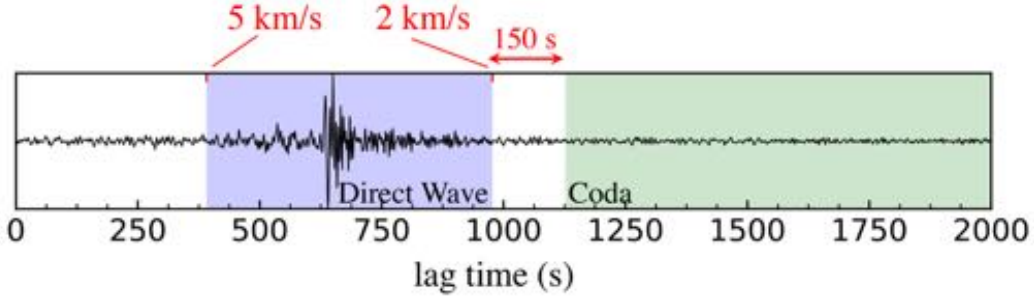


Figure 2. Example of the definition of the direct-wave and coda-wave segments of a two-station cross-correlation of ambient noise, C_2 , for stations ANMO (Albuquerque, NM) and M47A (Cromwell, NM), at an inter-station distance of ~ 1950 km. The direct-wave is the segment of the record between times corresponding to group speeds of 2 and 5 km/s. The coda-wave segment starts 150 s after the end of the direct-wave, and extends to the end of 3000 s. The symmetric component of the cross-correlation is shown (average of positive and negative correlation lags).

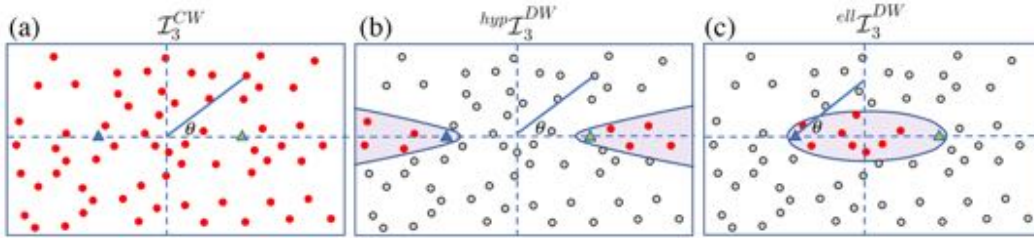


Figure 3. Schematic illustration of the geometrical constraints on source-stations for different methods of three-station interferometry. The two receiver-stations are shown with the blue and green triangles, and the circles are locations of other stations that may act as source-stations. Those stations that can act as source-stations are shown with red circles and those cannot with grey circles. (a) For three-station coda-wave interferometry, \mathcal{I}_3^{CW} , all stations whose operation overlaps the two receiver-stations can act as a source-station. (b) For three-station direct-wave interferometry with source-stations radially outside the receiver-stations, $^{hyp}\mathcal{I}_3^{DW}$, source-stations must lie in stationary phase hyperbolae (purple shading). (c) For three-station direct-wave interferometry with source-stations between the receiver-stations, $^{ell}\mathcal{I}_3^{DW}$, source-stations must lie in the stationary phase ellipse (purple shading). The angle θ in each case is defined in [section 3](#) and used in [Fig. 5](#).

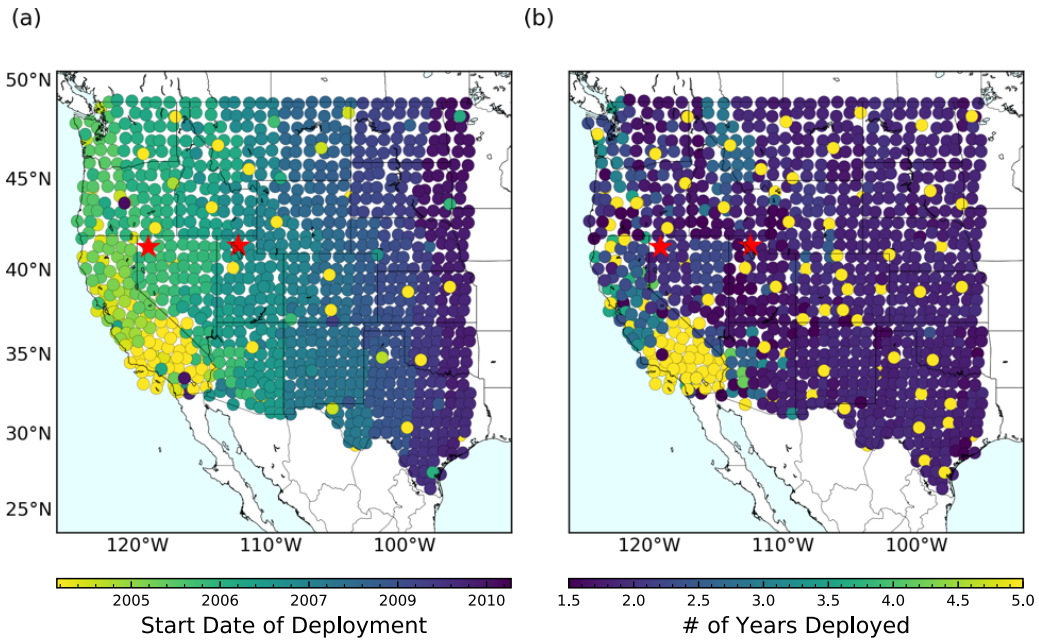


Figure 4. Map of stations used in this study. Red stars mark stations used in **Figs 5 - 7** and **18**: M07A (Soldier Meadow, NV) and M15A (Promontory, UT). (a) The start dates for each station are color-coded, showing a rolling pattern from west to east. (b) Duration of deployment is color-coded. Most stations are deployed around two years with a few much longer from the USArray Reference Network (`_US-REF`) and the Southern California Seismic Network (CI).

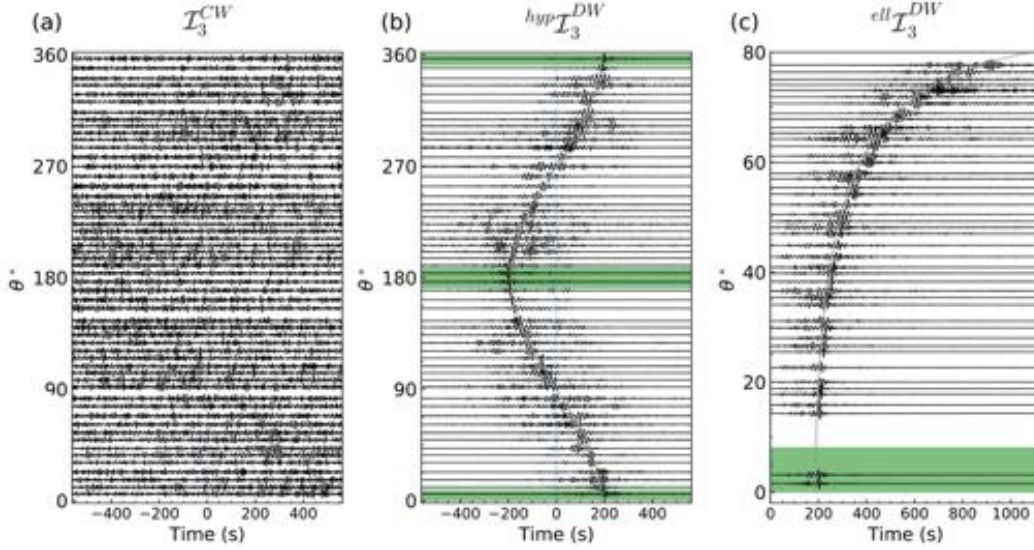


Figure 5. Example record sections of three-station interferograms for the receiver-station pair M07A-M15A, whose locations are shown in **Fig. 4**. (a) Coda-wave interferograms (C_3^{CW}) for different source-stations plotted at the azimuth angle θ shown in **Fig. 3a**. (b) Direct-wave interferograms (C_3^{DW}) plotted for source-stations at the azimuth angle shown in **Fig. 3b**. The green regions are the hyperbolic stationary-phase zones for $^{hyp}I_3^{DW}$. (c) Direct-wave interferograms (C_3^{DW}) plotted for source-stations at the azimuth angle shown in **Fig. 3c**. Only positive time lags are defined. The green region is the elliptical stationary-phase zone for $^{ell}I_3^{DW}$. Grey curves in (b) and (c) are predictions from eqs. (4) and (5), respectively, with $c = 3$ km/s. Only selected three-station interferograms are shown to ease visualization.

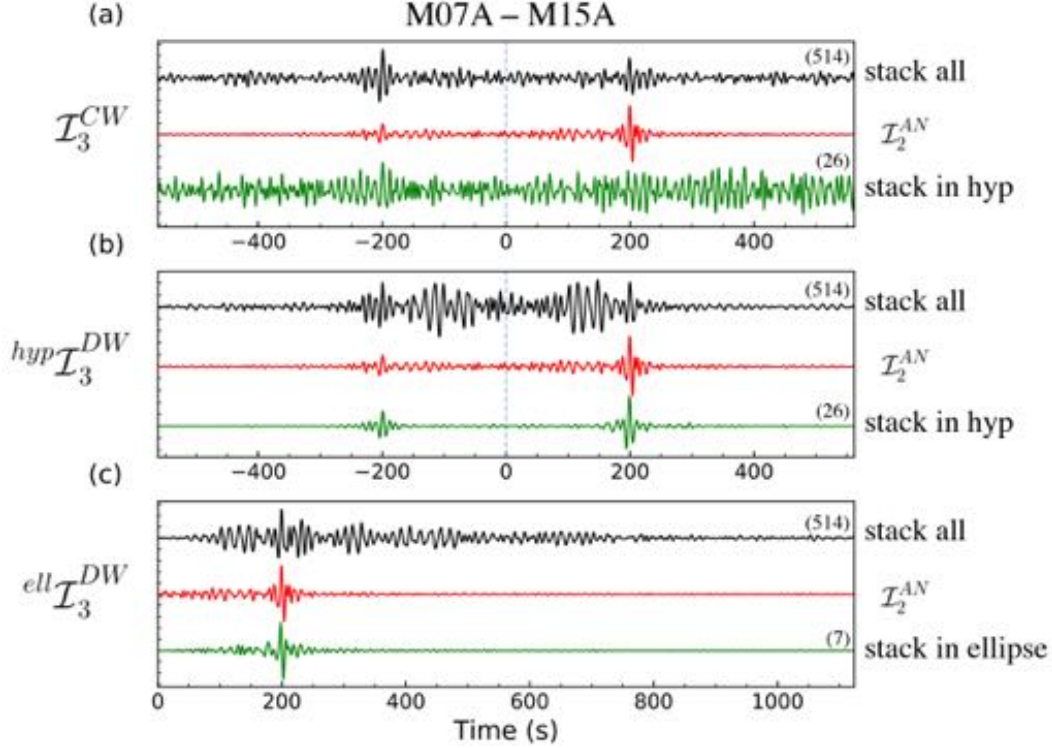


Figure 6. Examples of stacks of three-station interferograms for the receiver-station pair M07A-M15A of **Fig. 5**. In each panel the two-station estimated Green’s function (\mathcal{I}_2^{AN}) is plotted for reference (red). The number of source-stations for each stack is shown in parentheses above the stacked trace. (a) Method \mathcal{I}_3^{CW} . Two stacks of coda-wave interferograms are shown: (black line, stack all) stack of the interferograms from all source-stations irrespective of the azimuthal angle θ (defined in **Fig. 3a**) and (green line, stack hyp) stack of the coda-wave interferograms for sources in the hyperbolic stationary phase zone. For \mathcal{I}_3^{CW} , the black line is the composite Green’s function. (b) Method $^{hyp}\mathcal{I}_3^{DW}$. Black and green lines have similar meanings to those in (a), but here the direct-wave interferograms are stacked. For $^{hyp}\mathcal{I}_3^{DW}$, the green line is the composite Green’s function. (c) Method $^{ell}\mathcal{I}_3^{DW}$. Black line is the same as in (b), but the green line is the stack of direct-wave interferograms in the elliptical stationary phase zone. For $^{ell}\mathcal{I}_3^{DW}$, the green line is the composite Green’s function and only positive time lags are defined.

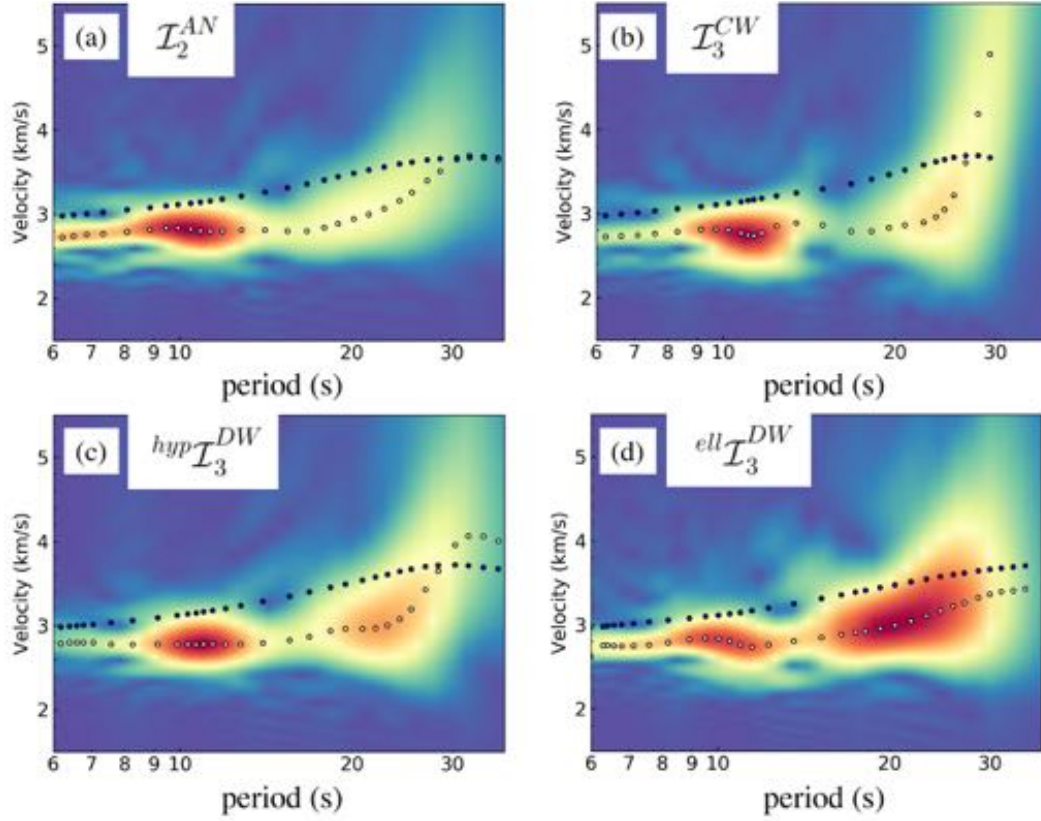


Figure 7. Frequency-time analysis (FTAN) diagrams for the receiver pair M07A-M15A using the waveforms from **Fig. 6**: (a) \mathcal{I}_2^{AN} , (b) \mathcal{I}_3^{CW} , (c) $^{hyp}\mathcal{I}_3^{DW}$, and (d) $^{ell}\mathcal{I}_3^{DW}$. White and blue circles are group and phase speed measurements, respectively.

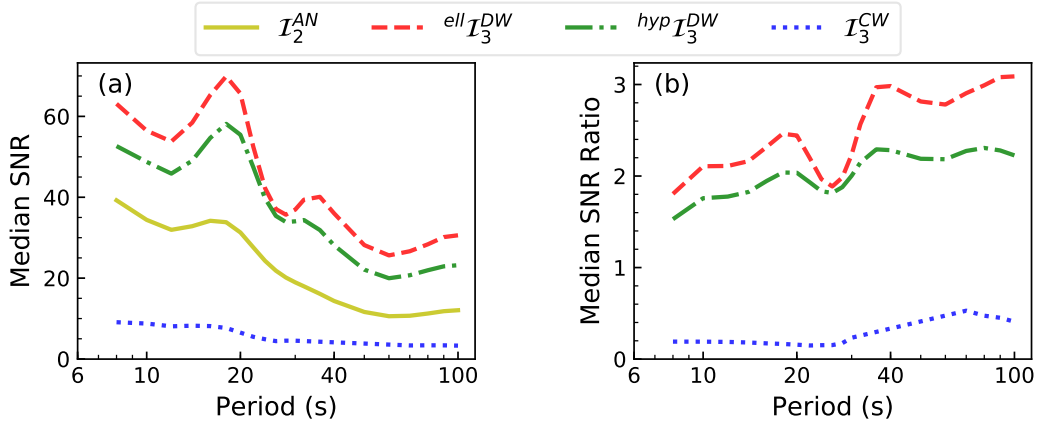


Figure 8. Signal-to-noise ratio (SNR) of estimated Green’s functions for the different interferometric methods (see legend) plotted versus period. (a) Median of the SNR for each method taken over all measurements at each period. SNR generally decreases with period for all methods, but the highest SNR is from the three-station direct-wave method with an elliptical stationary phase zone ($ell\mathcal{I}_3^{DW}$) and the lowest is from the three-station coda-wave method (\mathcal{I}_3^{CW}). (b) Paths common to two-station and three-station interferometry in (a) are selected such that the ratio of the median SNR for each three-station method to that for the two-station method is shown. The direct-wave methods increase SNR relative to \mathcal{I}_2^{AN} by a factor ranging from about 1.5 to 3 which grows with period, whereas the coda-wave method reduces SNR by a factor of 3-5.

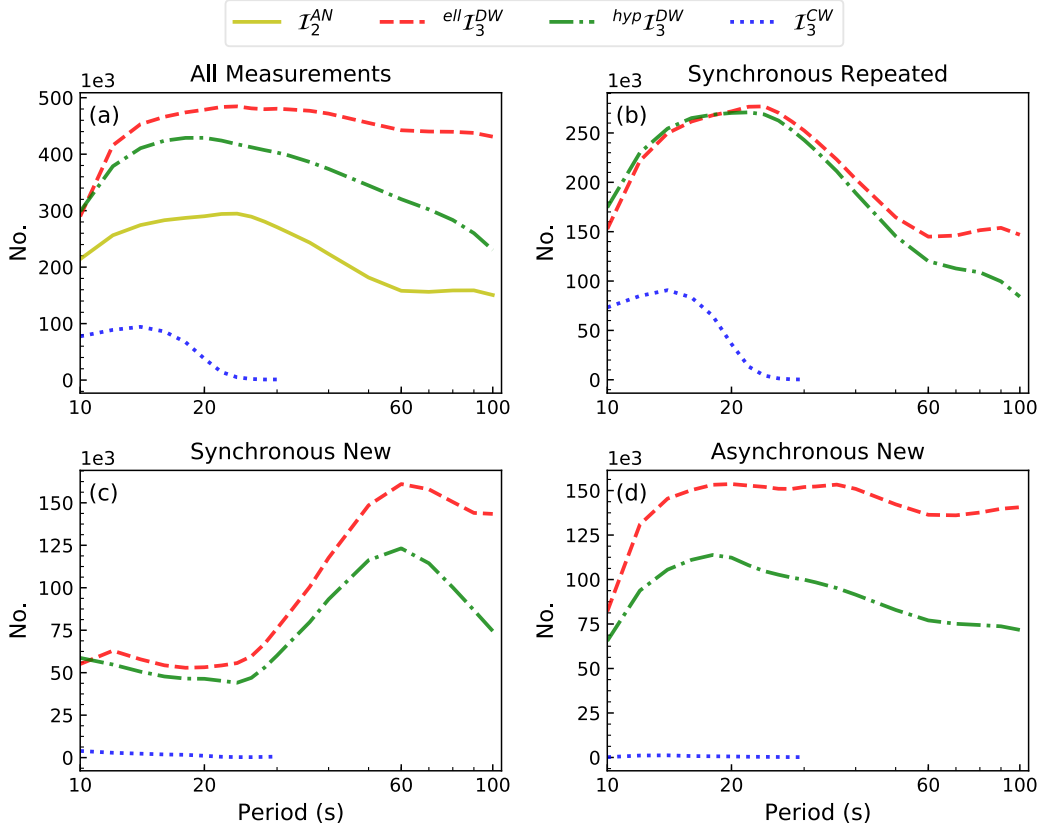


Figure 9. Number of measurements versus period. (a) Number of accepted Rayleigh wave phase speed measurements plotted versus period for the different interferometric methods (see legend). The largest number of measurements is from the three-station direct-wave method with an elliptical stationary phase zone ($ell \mathcal{I}_3^{DW}$) and the smallest number is from the three-station coda-wave method (\mathcal{I}_3^{CW}). The total number of measurements can be broken into three parts, as shown in (b)-(d). (b) Number of synchronous measurements from three-station interferometry methods (\mathcal{I}_3) that are non-existent for two-station interferometry \mathcal{I}_2^{AN} (because of low SNR). (c) Number of asynchronous measurements from \mathcal{I}_3 that are non-existent for \mathcal{I}_2^{AN} (because of asynchrony). (d) Number of measurements from \mathcal{I}_3 that are redundant for \mathcal{I}_2^{AN} .

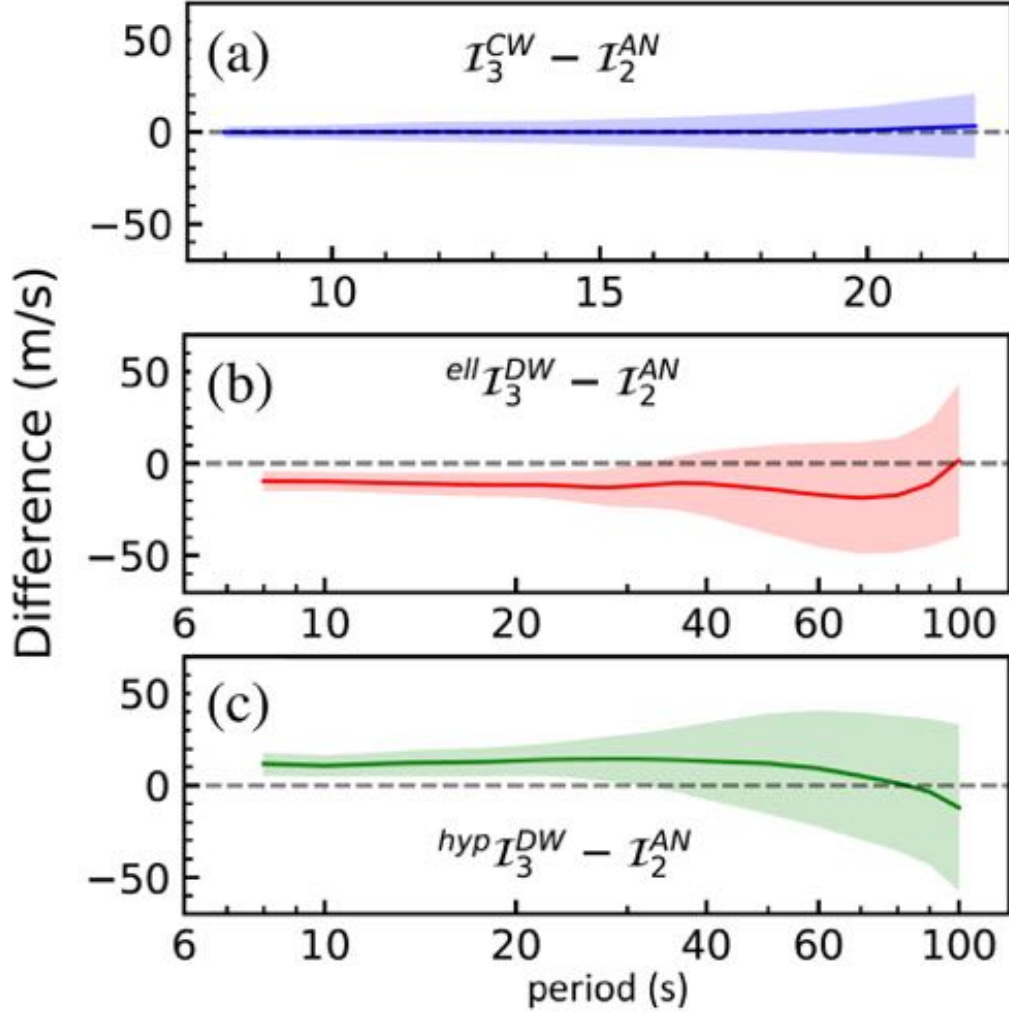


Figure 10. Fig. depicting the mean and standard deviation of the difference between Rayleigh wave phase speed measurements from the three-station methods (\mathcal{I}_3) and the two-station (\mathcal{I}_2^{AN}) method. No bias correction has been applied. Measurements from the direct-wave three-station methods (\mathcal{I}_3^{DW}) are systematically shifted from the \mathcal{I}_2^{AN} measurements, albeit with different signs, whereas the coda-wave measurements (\mathcal{I}_3^{CW}) are not shifted relative to those from \mathcal{I}_2^{AN} . The standard deviation of the differences between the three-station and two-station measurements grow with period.

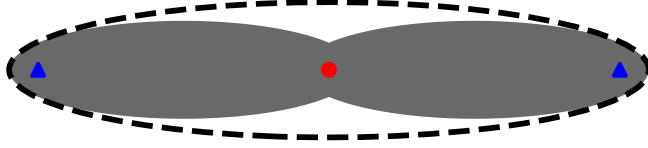
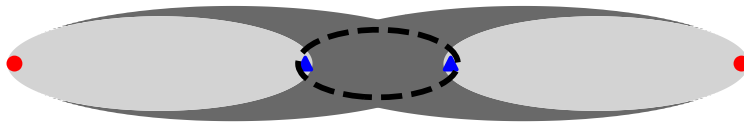
(a) $ell\mathcal{I}_3^{DW}$ (b) $hyp\mathcal{I}_3^{DW}$ 

Figure 11. Schematic illustration contrasting the sensitivity kernels for $ell\mathcal{I}_3^{DW}$ and $hyp\mathcal{I}_3^{DW}$ with that for \mathcal{I}_2 which is shown as a Fresnel ellipse encompassing the two receiver-stations (blue triangles) and is depicted with the dashed lines. (a) The sensitivity kernel for $ell\mathcal{I}_3^{DW}$ is a superposition of the two elliptical Fresnel zones where the source-station (red dot) is at one focus and each of the receiver-stations are at the other foci. The resulting sensitivity kernel for $ell\mathcal{I}_3^{DW}$ (grey region) is smaller than the kernel for \mathcal{I}_2 (zone encompassed by the dashed line). (b) The sensitivity kernel for $hyp\mathcal{I}_3^{DW}$ is the difference of the two elliptical Fresnel zones where each source-station (red dots) is at one focus and each of the receiver-stations is at the other focus. The resulting sensitivity kernel for $hyp\mathcal{I}_3^{DW}$ (grey region) is more complicated and larger than the kernel for \mathcal{I}_2 (zone encompassed by the dashed line).

10 s

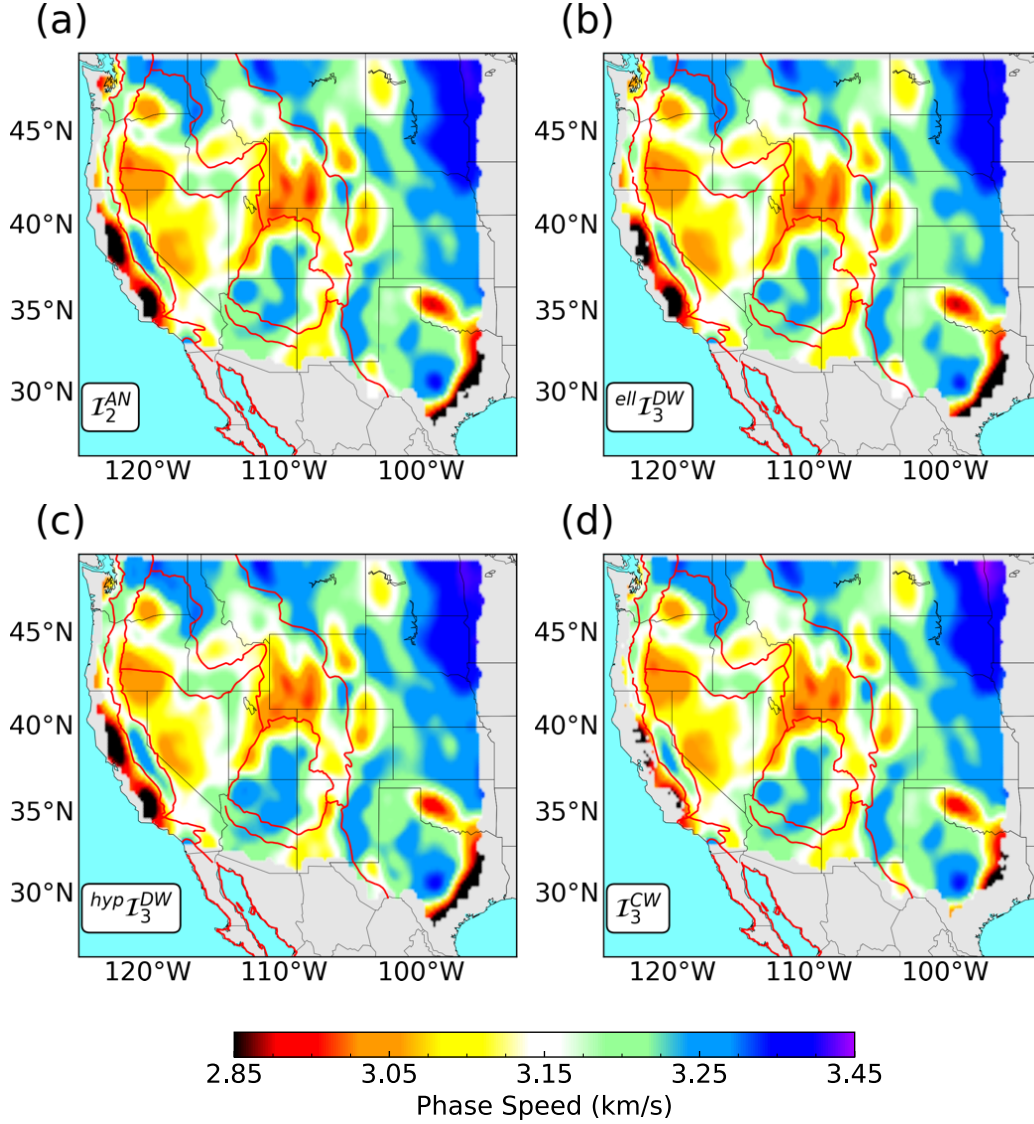


Figure 12. Rayleigh wave phase speed maps constructed with eikonal tomography at 10 s period using four different interferometric methods: (a) traditional two-station ambient noise interferometry (I_2^{AN}), (b) three-station direct-wave interferometry with elliptical stationary phase zone ($ell I_3^{DW}$), (c) three-station direct-wave interferometry with hyperbolic stationary phase zone ($hyp I_3^{DW}$), and (d) three-station coda-wave interferometry (I_3^{CW}). Red lines depict geological provinces (Fenneman & Johnson, 1946).

20 s

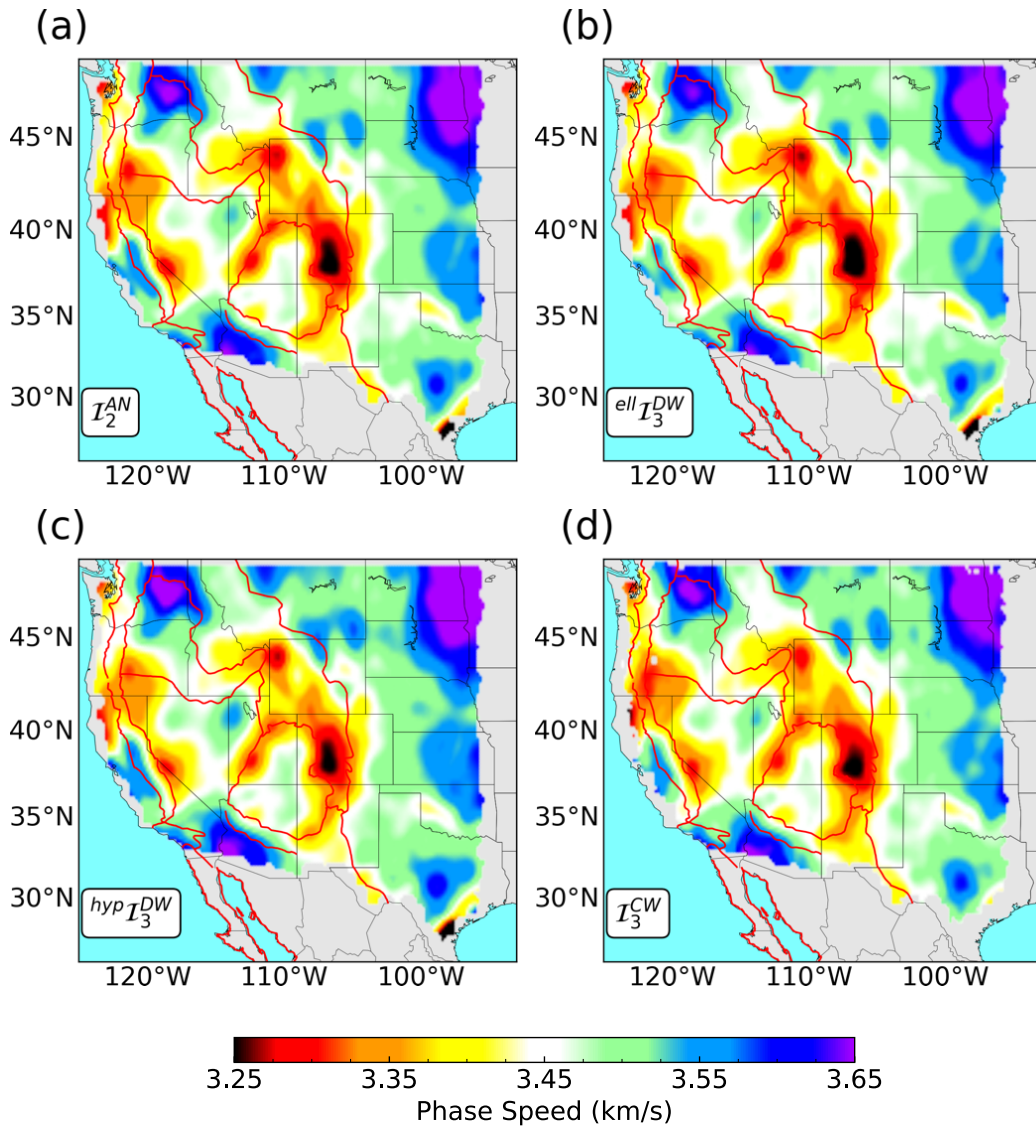


Figure 13. Similar to Fig. 12, but at 20 s period.

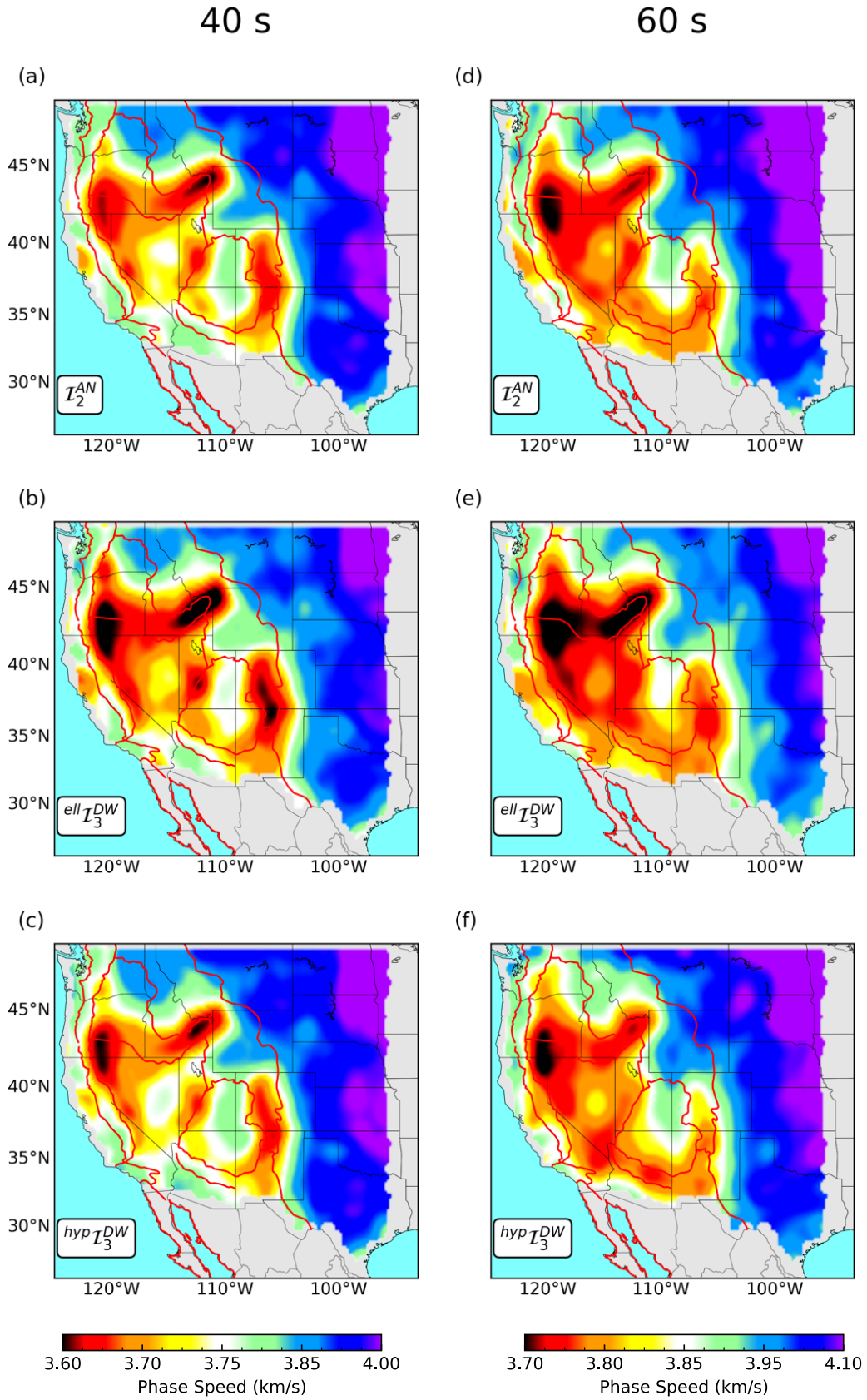


Figure 14. Similar to Fig. 12, but at periods of 40 and 60 s. I_3^{CW} yielded too few measurements to produce a tomographic map at these periods.

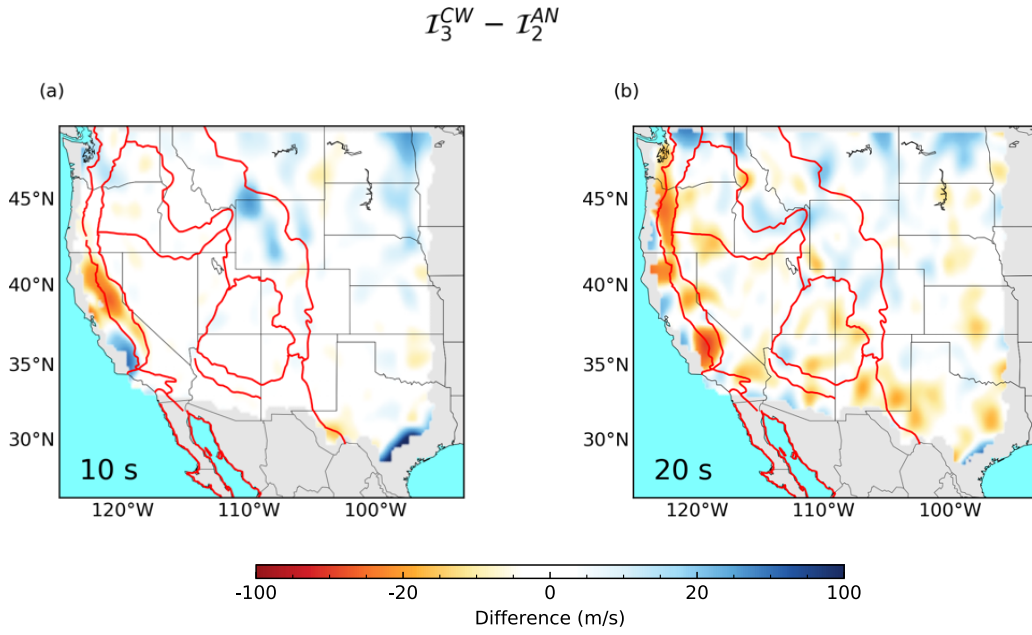


Figure 15. Differences in Rayleigh wave phase speed maps (Figs 12 and 13) between three-station coda-wave interferometry (\mathcal{I}_3^{CW}) and two-station ambient noise interferometry (\mathcal{I}_2^{AN}).

\mathcal{I}_3^{CW} yields too few measurements to produce tomographic maps at longer periods.

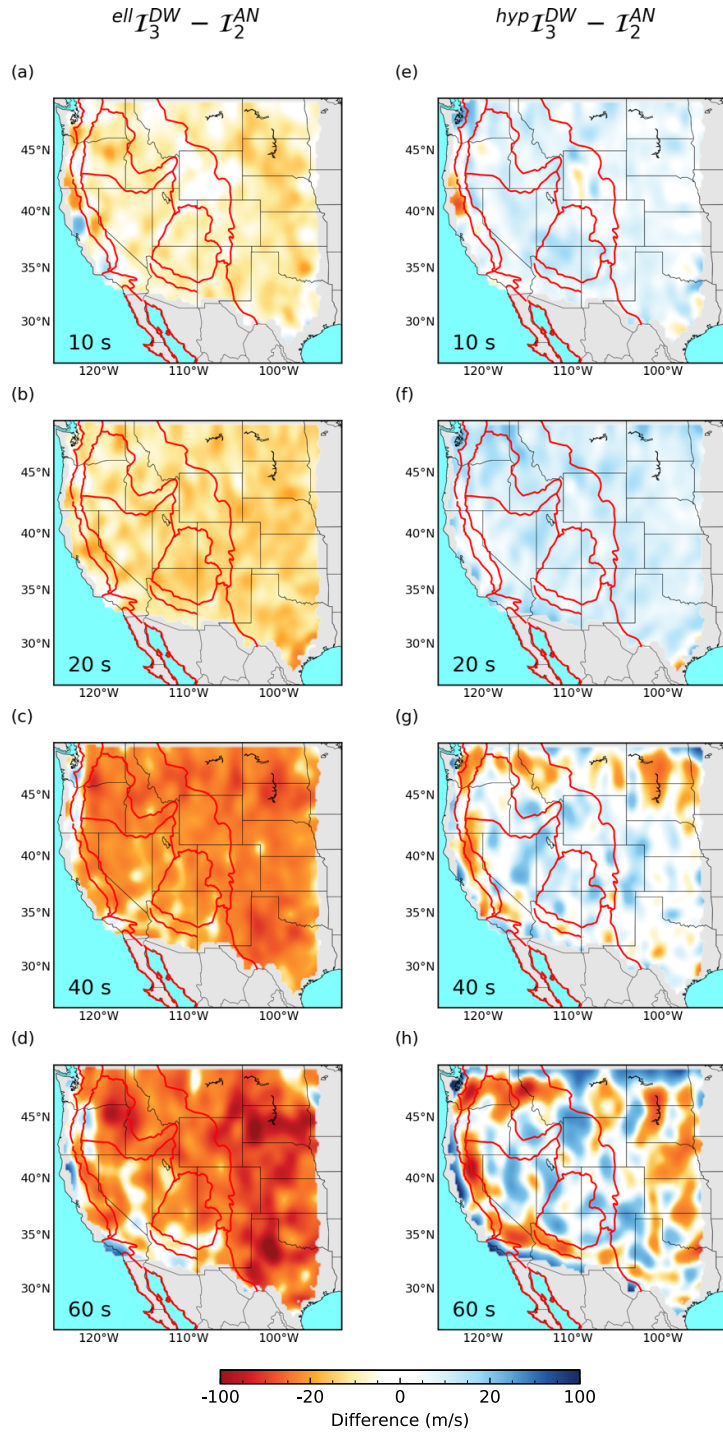


Figure 16. Similar to **Fig. 15** except differences are between three-station direct-wave interferometry and \mathcal{I}_2^{AN} (**Figs 12 - 14**), and results are presented at four periods: 10 s, 20 s, 40 s, and 60 s. (a)-(d) The $ell \mathcal{I}_3^{DW}$ maps are systematically slower relative to the \mathcal{I}_2^{AN} maps and the standard deviation of the difference increases with period. (e)-(h) The $hyp \mathcal{I}_3^{DW}$ maps are systematically faster relative to the \mathcal{I}_2^{AN} maps and the standard deviation of the difference increases with period.

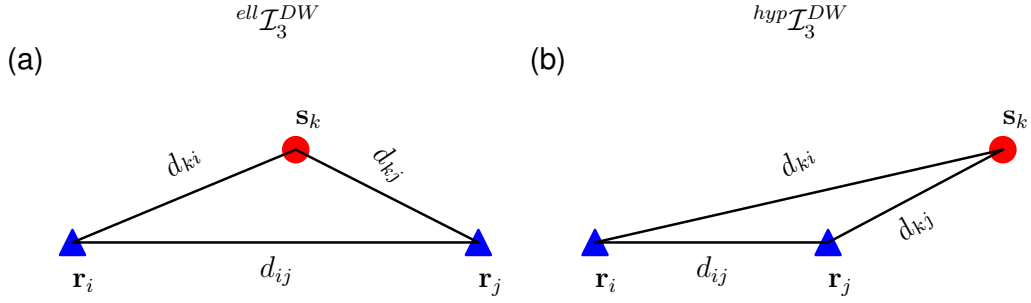


Figure 17. Geometry of the source-station (s_k) and receiver-stations (r_i, r_j) used to determine the bias correction for the three-station direct-wave methods: (a) $ell\mathcal{I}_3^{DW}$ and (b) $hyp\mathcal{I}_3^{DW}$.

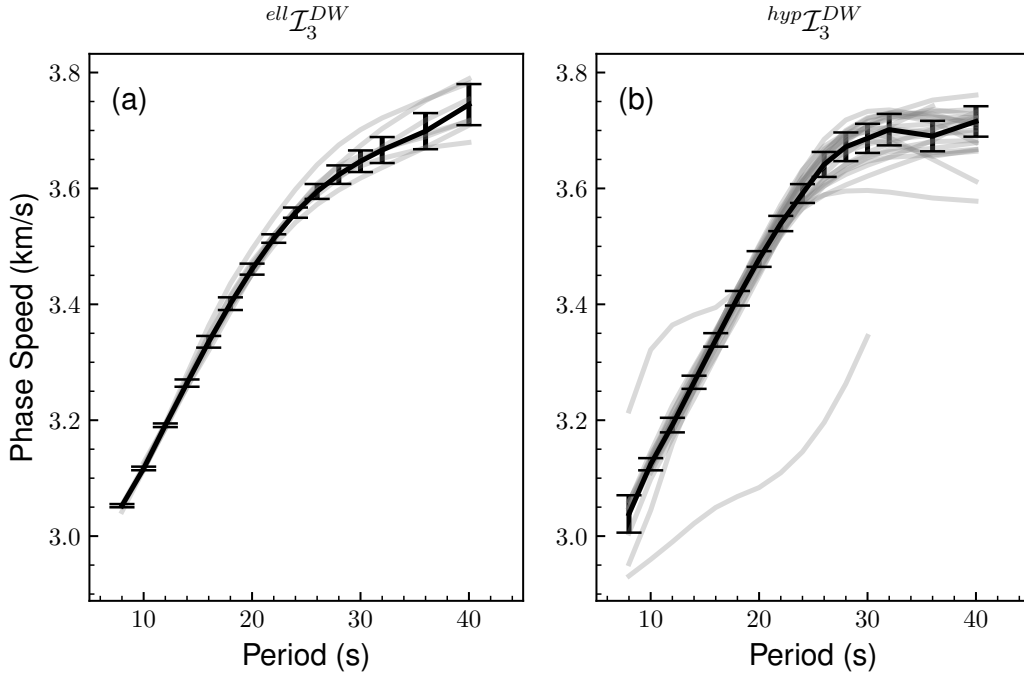


Figure 18. Examples of the de-biased Rayleigh wave phase speed curves for the receiver-station pair M07A-M15A for the two three-station direct-wave methods: (a) $ell\mathcal{I}_3^{DW}$ and (b) $hyp\mathcal{I}_3^{DW}$. Each gray curve is measured on a single source-specific interferogram, where there are 7 source-stations for $ell\mathcal{I}_3^{DW}$ and 26 source-stations for $hyp\mathcal{I}_3^{DW}$. The mean and standard deviation of the constituent curves are plotted with the black line and error bars, respectively.

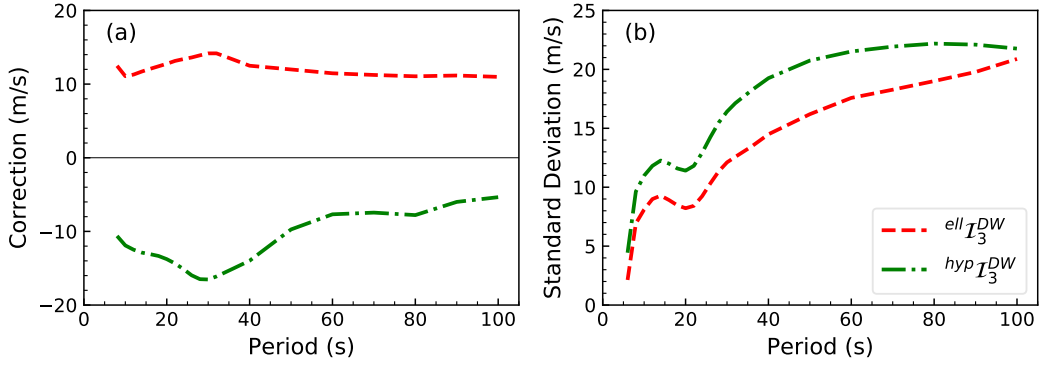


Figure 19. (a) Mean de-biasing correction averaged over all receiver-station pairs in the data set for $ell \mathcal{I}_3^{DW}$ (red line) and $hyp \mathcal{I}_3^{DW}$ (green line). (b) Standard deviation of the de-biased dispersion curves averaged over all receiver-station pairs in the data set.

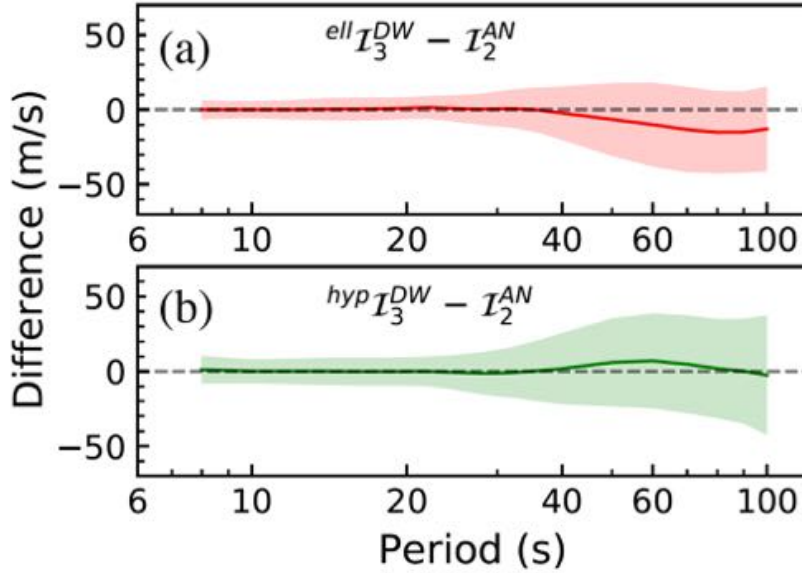


Figure 20. Similar to **Fig. 10**, but the three-station direct-wave methods (\mathcal{I}_3^{DW}) have been de-biased based on ray-theory. Systematic differences in Rayleigh wave phase speed measurements compared to the \mathcal{I}_2^{AN} method are largely removed at periods below 40 s, and are reduced at all periods below 80 s compared to the uncorrected values. The standard deviation of the differences between the three-station and two-station measurements are not appreciably affected by the de-biasing correction.